算法设计与分析(2024年春季学期) Greedy Algorithms

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Trivial Algorithm for an Optimization Problem

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Goals of algorithm design

- Design efficient algorithms to solve problems
- Design more efficient algorithms to solve problems

Common Paradigms for Algorithm Design

- Greedy Algorithms
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- Dynamic Programming
- Greedy algorithms are often for optimization problems.
- They often run in polynomial time due to their simplicity.

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Def. A strategy is safe: there is always an optimum solution that agrees with the decision made according to the strategy.

Outline

- 1 Toy Example: Box Packing
- Interval Scheduling
- Scheduling to Minimize Lateness
- 4 Weighted Completion Time Scheduling
- Offline Caching
 - Heap: Concrete Data Structure for Priority Queue
- 6 Data Compression and Huffman Code
- Summary

Box Packing

Input: n boxes of capacities c_1, c_2, \cdots, c_n m items of sizes s_1, s_2, \cdots, s_m Can put at most 1 item in a box
Item j can be put into box i if $s_i \leq c_i$

Output: A way to put as many items as possible in the boxes.

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Example:

• Box capacities: 60, 40, 25, 15, 12

• Item sizes: 45, 42, 20, 19, 16

• Can put 3 items in boxes: $45 \rightarrow 60, 20 \rightarrow 40, 19 \rightarrow 25$

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Designing a Reasonable Strategy for Box Packing

- Q: Take box 1. Which item should we put in box 1?
- A: The item of the largest size that can be put into the box.

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- Prove that the reasonable strategy is "safe"
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• Intuition: putting the item gives us the easiest residual problem.

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- formal proof via exchanging argument:

Proof.

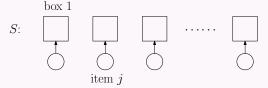
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- Let j = largest item that box 1 can hold.
- ullet Take any optimum solution S. If j is put into Box 1 in S, done.

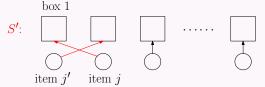
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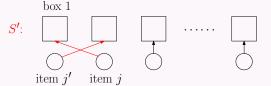
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- $s_{j'} \leq s_j$, and swapping gives another solution S'
- S' is also an optimum solution. In S', j is put into Box 1.

• Notice that the exchanging operation is only for the sake of analysis; it is not a part of the algorithm.

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A Common Way to Analyze Greedy Algorithms

- Prove that the reasonable strategy is "safe"
- Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem
- Trivial: we decided to put Item j into Box 1, and the remaining instance is obtained by removing Item j and Box 1.

Generic Greedy Algorithm

- 1: while the instance is non-trivial do
- 2: make the choice using the greedy strategy
- 3: reduce the instance

Greedy Algorithm for Box Packing

- 1: $T \leftarrow \{1, 2, 3, \cdots, m\}$
- 2: **for** $i \leftarrow 1$ to n **do**
- 3: **if** some item in T can be put into box i **then**
- 4: $j \leftarrow$ the largest item in T that can be put into box i
- 5: print("put item j in box i")
- 6: $T \leftarrow T \setminus \{j\}$

Exchange argument: Proof of Safety of a Strategy

- ullet let S be an arbitrary optimum solution.
- ullet if S is consistent with the greedy choice, done.
- otherwise, show that it can be modified to another optimum solution S' that is consistent with the choice.

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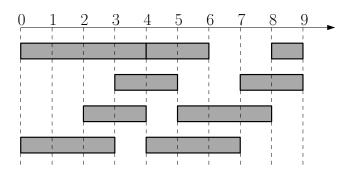
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Interval Scheduling

Input: n jobs, job i with start time s_i and finish time f_i

i and j are compatible if $[s_i,f_i)$ and $[s_j,f_j)$ are disjoint

Output: A maximum-size subset of mutually compatible jobs

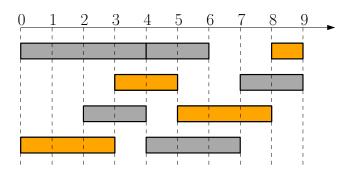


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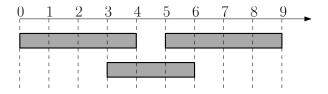


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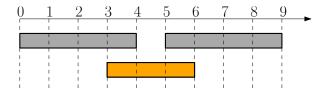
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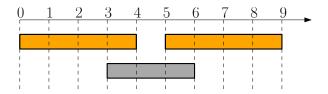
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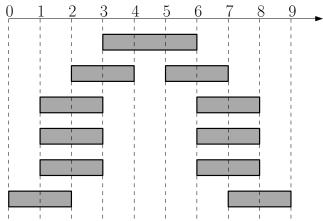


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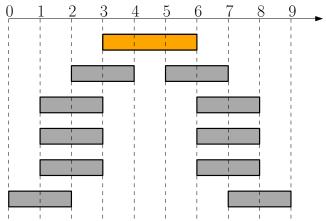
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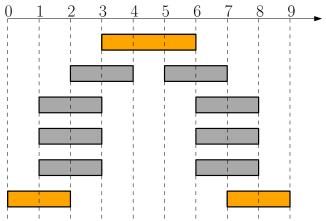
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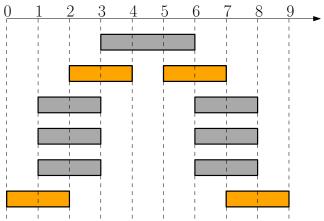
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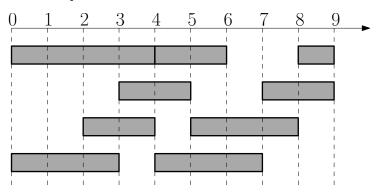


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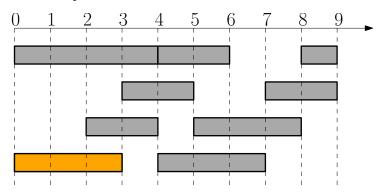
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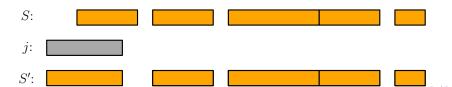
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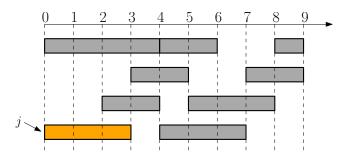
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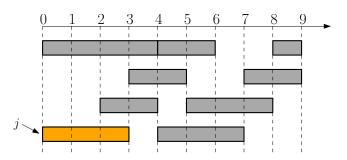
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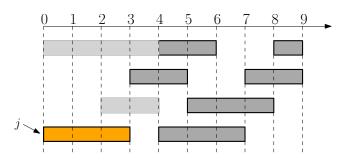
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- Is it another instance of interval scheduling problem?



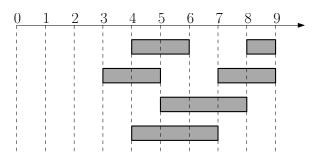
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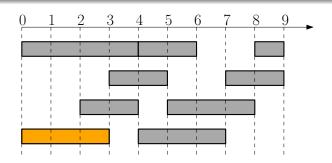


Schedule(s, f, n)

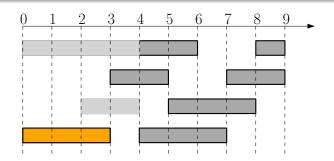
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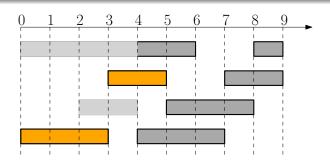
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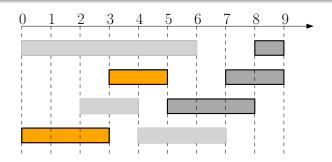
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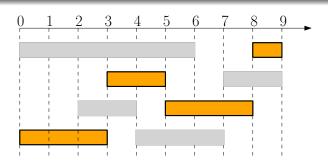
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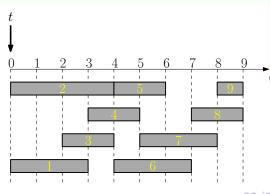
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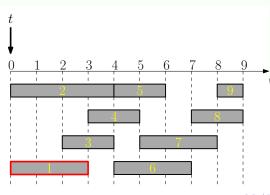
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- Clever implementation: $O(n \lg n)$ time

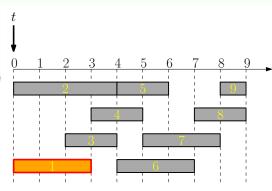
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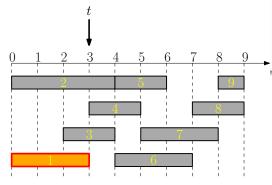
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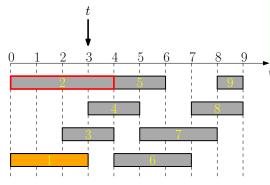
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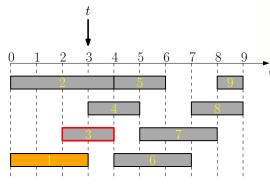
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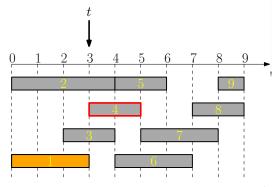
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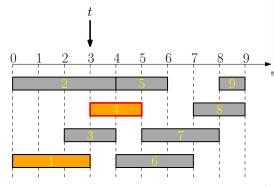
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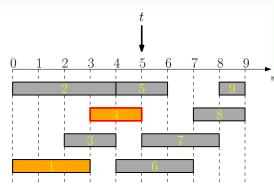
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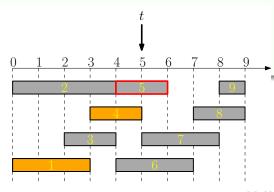
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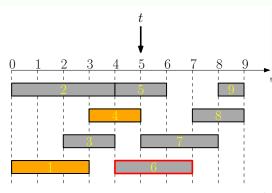
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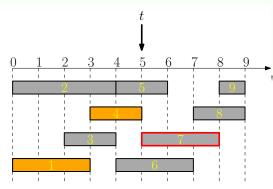
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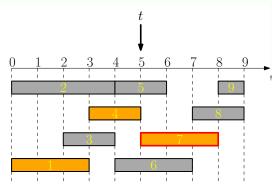
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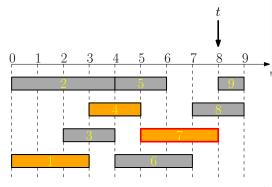
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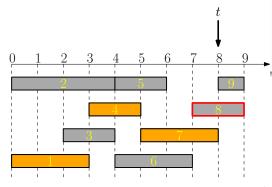
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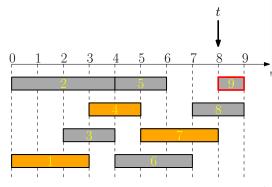
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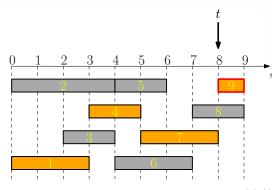
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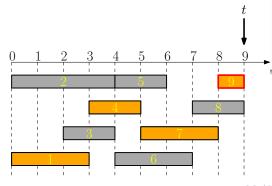
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Scheduling to minimize lateness

Input: n jobs, each job $j \in [n]$ with a processing time p_j and deadline d_i

Output: schedule jobs on 1 machine, to minimize the max. lateness C_i : completion time of j lateness $l_i := \max\{C_i - d_i, 0\}$

• Example input:

j	а	b	С	d
$\overline{p_j}$	3	3	2	1
$\overline{d_j}$	5	7	4	8

	0	1	2	3	4	5	6	7	8	9	10	►
solution 1		í	ı])		С		\Box		
solution 2		С		í	a])		\Box		

- solution 1: max lateness = $\max\{0, 3 5, 6 7, 8 4, 9 8\} = 4$
- solution 2: max lateness = $\max\{0, 2-4, 5-5, 8-7, 9-8\} = 1$
- solution 2 is better

Candidate algorithms

Schedule the jobs in some natural order. Which order should we choose?

- lacktriangle Ascending order of processing times p_j
- **8** Ascending order of slackness $d_j p_j$
- **O** Ascending order of deadline d_j .

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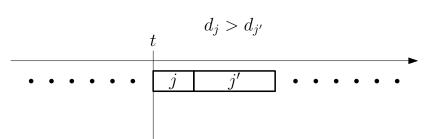
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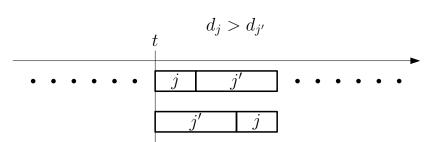
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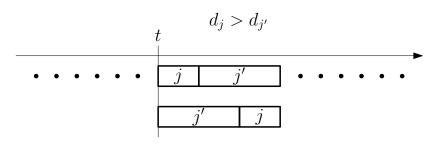
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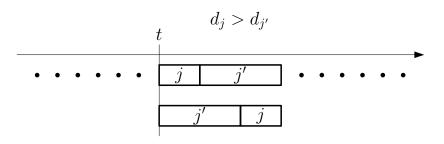
Lemma The ascending order of deadlines d_j (the Earliest Deadline First order or the EDF order) is the optimum schedule.



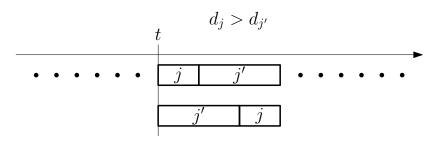




• before: $\max\{t + p_j - d_j, t + p_j + p_{j'} - d_{j'}\} = t + p_j + p_{j'} - d_{j'}$

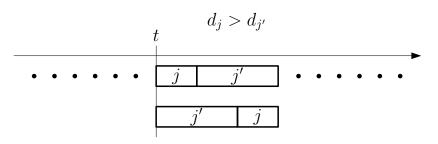


- before: $\max\{t + p_j d_j, t + p_j + p_{j'} d_{j'}\} = t + p_j + p_{j'} d_{j'}$
- after: $\max\{t + p_{j'} d_{j'}, t + p_j + p_{j'} d_j\}$



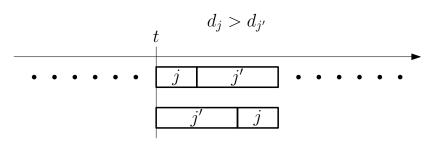
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- $\bullet \ p_{j'} d_{j'} < p_j + p_{j'} d_{j'} \ \text{and} \ p_j + p_{j'} d_j < p_j + p_{j'} d_{j'}$

• maximum lateness = $\max \left\{ 0, \max_{j \in [n]} \{C_j - d_j\} \right\}$.



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- $\max\{t + p_{j'} d_{j'}, t + p_j + p_{j'} d_j\} < t + p_j + p_{j'} d_{j'}$
- after swapping, the maximum of the two terms strictly decreases

- 1: let S be any schedule (i.e, a permutation of [n])
- 2: **while** there are two adjacent jobs j and j' in S, with j before j' and $d_j > d_{j'}$ **do**
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• (j, j') is an inversion in S if j appears before j' and $d_j > d_{j'}$.

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- **Q:** What if there are multiple EDF orders, i.e., some jobs have the same deadline?
- A: All EDF orders have the same maximum lateness.

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Scheduling to Minimize Weighted Completion Time

Input: A set of n jobs $[n] := \{1, 2, 3, \dots, n\}$

each job j has a weight \boldsymbol{w}_j and processing time \boldsymbol{p}_j

Output: an ordering of jobs so as to minimize the total weighted

completion time of jobs

$$p_{\mathbf{a}} = 1$$

$$\mathbf{a}$$

$$w_1 = 2$$

$$p_{\mathbf{b}} = 2$$

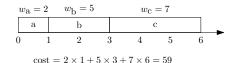
$$\mathbf{b}$$

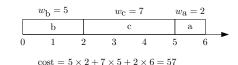
$$w_2 = 5$$

$$p_{C} = 3$$

$$c$$

$$w_{3} = 7$$





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- lacksquare Descending order of slackness w_j
- Ascending order of $p_j w_j$
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- **②** Ascending order of p_j/w_j

Def. The Smith ratio of a job is w_j/p_j .

Lemma The descending order of Smith ratios (the Smith rule) is optimum.

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• Therefore, swapping decrease the weighted completion time if $\frac{p_{j'}}{w_{i'}}<\frac{p_j}{w_j}$.

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- Therefore, swapping decrease the weighted completion time if $\frac{p_{j'}}{w_{i'}} < \frac{p_j}{w_j}$.
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- Indeed, optimum weighted completion time is

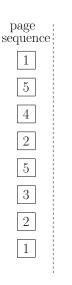
$$\sum_{j \in [n]} w_j p_j + \sum_{1 \leq j < j' \leq n} \min \{ w_j p_{j'}, w_{j'} p_j \}.$$

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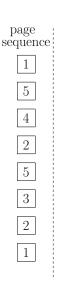
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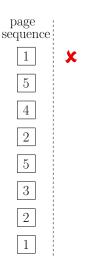
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 We need bring the page into cache, and evict some existing page if necessary.



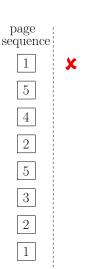
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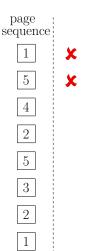


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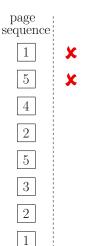


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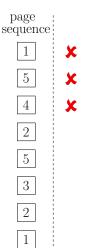


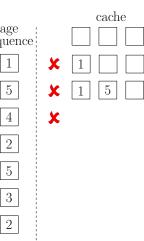
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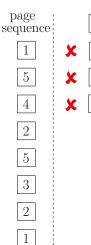


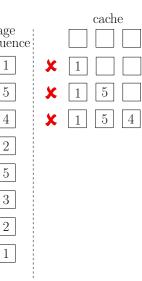
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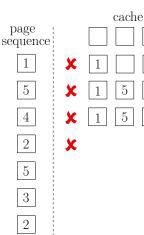


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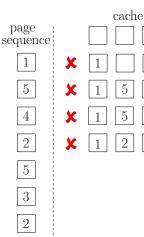




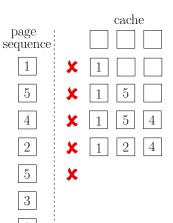
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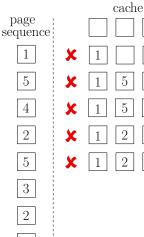
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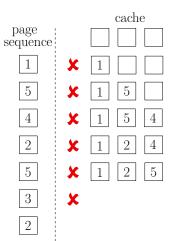
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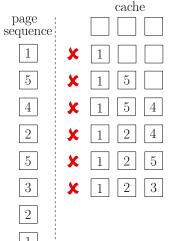
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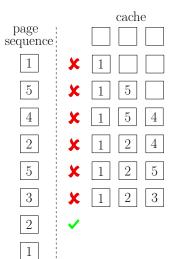
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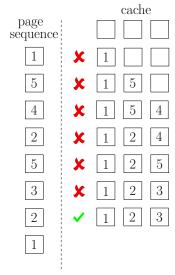
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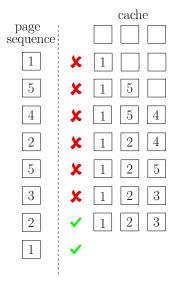
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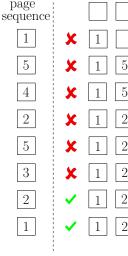
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cache

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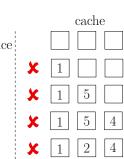




misses = 6

- ullet Cache that can store k pages
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 We need bring the page into cache, and evict some existing page if necessary.
- Cache hit happens if requested page already in cache.
- Goal: minimize the number of cache misses.



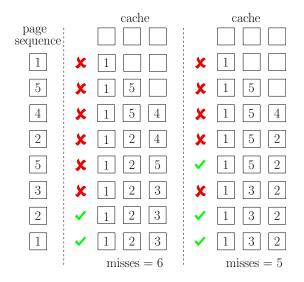






misses = 6

A Better Solution for Example



Input: k: the size of cache n: number of pages We use [n] for $\{1,2,3,\cdots,n\}$.

 $\rho_1, \rho_2, \rho_3, \cdots, \rho_T \in [n]$: sequence of requests

Output: $i_1, i_2, i_3, \dots, i_T \in \{\text{hit}, \text{empty}\} \cup [n]$: indices of pages to evict ("hit" means evicting no page, "empty" means

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- Offline Caching: we know the whole sequence ahead of time.
- Online Caching: we have to make decisions on the fly, before seeing future requests.

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Q: Which one is more realistic?

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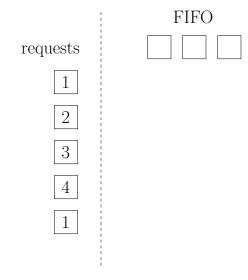
A: Use the offline solution as a benchmark to measure the "competitive ratio" of online algorithms

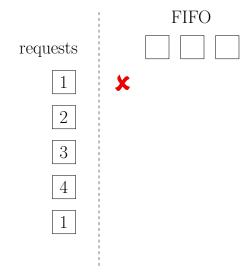
• FIFO(First-In-First-Out): always evict the first page in cache

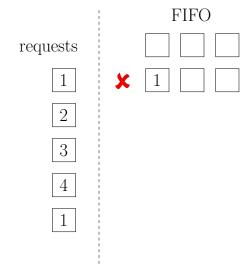
- FIFO(First-In-First-Out): always evict the first page in cache
- LRU(Least-Recently-Used): Evict page whose most recent access was earliest

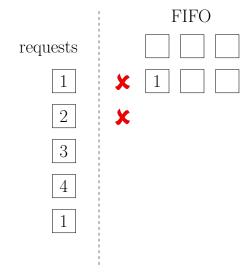
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- LFU(Least-Frequently-Used): Evict page that was least frequently requested

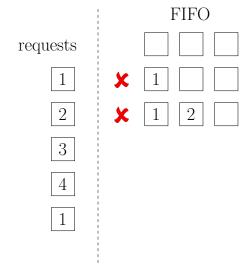
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- All the above algorithms are not optimum!
- Indeed all the algorithms are "online", i.e, the decisions can be made without knowing future requests. Online algorithms can not be optimum.

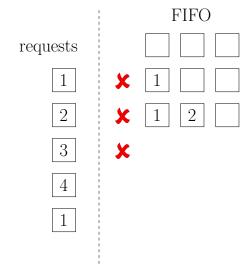


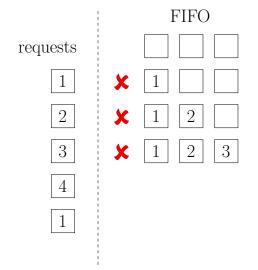


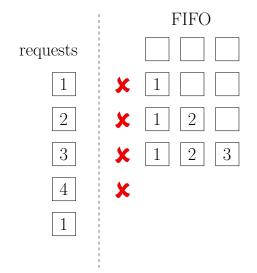


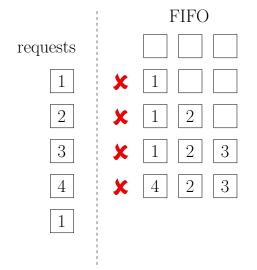


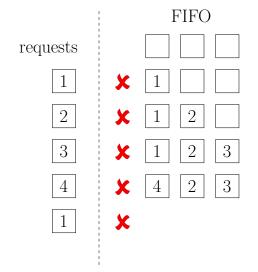


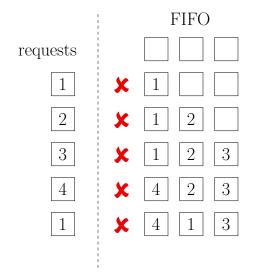


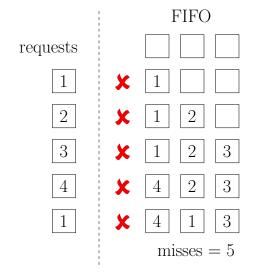


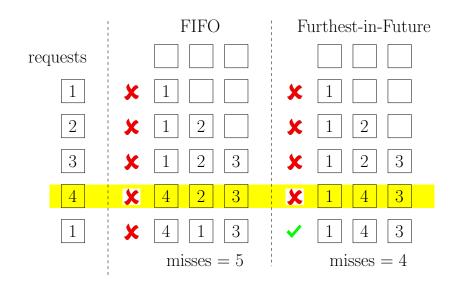










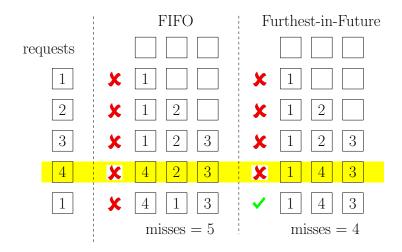


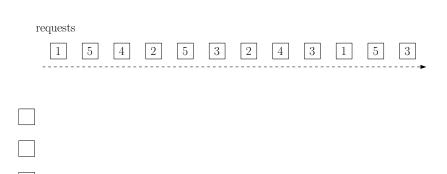
Optimum Offline Caching

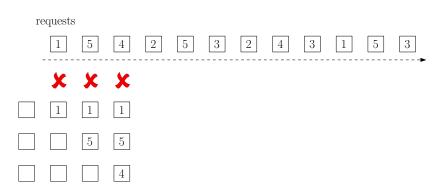
Furthest-in-Future (FF)

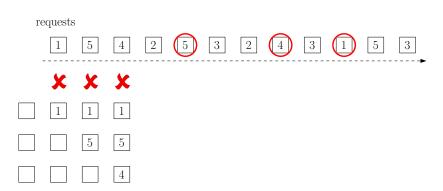
- Algorithm: every time, evict the page that is not requested until furthest in the future, if we need to evict one.
- The algorithm is **not** an online algorithm, since the decision at a step depends on the request sequence in the future.

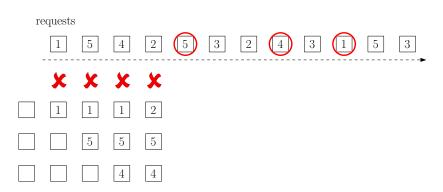
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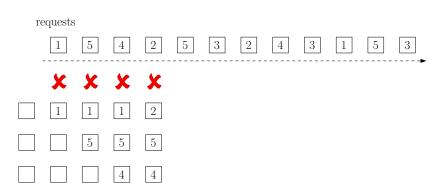


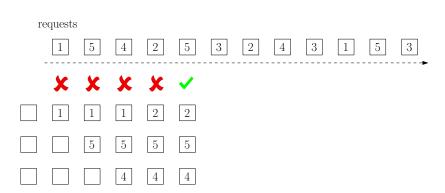


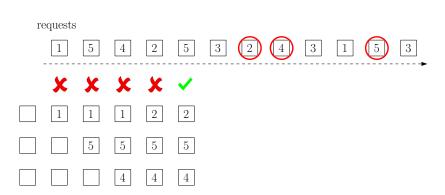


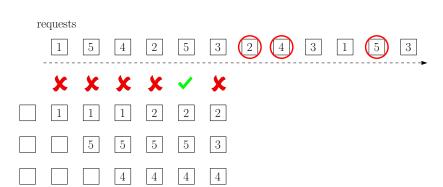


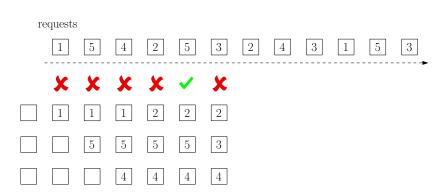


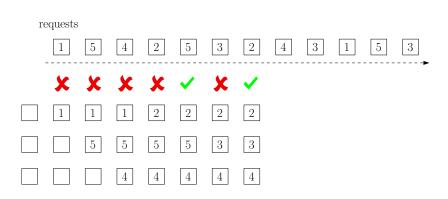


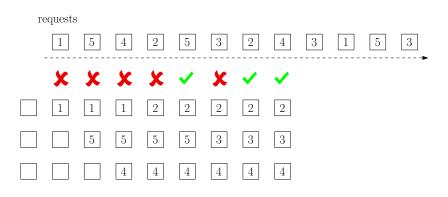


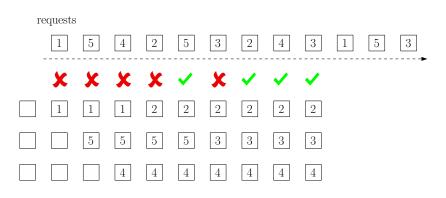


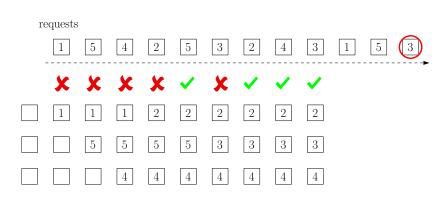


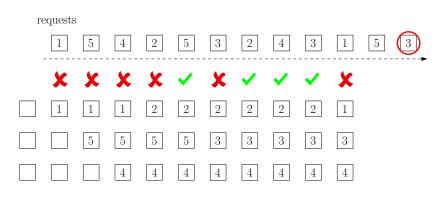


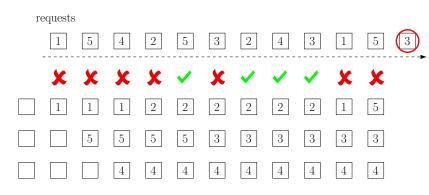


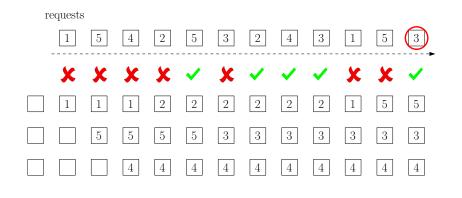












Recall: Designing and Analyzing Greedy Algorithms

Greedy Algorithm

- Build up the solutions in steps
- At each step, make an irrevocable decision using a "reasonable" strategy

A Common Way to Analyze Greedy Algorithms

- Prove that the reasonable strategy is "safe" (key)
- Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem (usually easy)

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Offline Caching Problem

Input: k: the size of cache

n: number of pages

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Output: $i_1, i_2, i_3, \cdots, i_t \in \{\text{hit}, \text{empty}\} \cup [n]$

- empty stands for an empty page
- "hit" means evicting no pages

Offline Caching Problem

```
Input: k: the size of cache n: number of pages \rho_1, \rho_2, \rho_3, \cdots, \rho_T \in [n]: sequence of requests p_1, p_2, \cdots, p_k \in \{\text{empty}\} \cup [n]: initial set of pages in cache
```

- **Output:** $i_1, i_2, i_3, \dots, i_t \in \{\text{hit}, \text{empty}\} \cup [n]$
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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. It is safe to evict p^* at time 1.

A Common Way to Analyze Greedy Algorithms

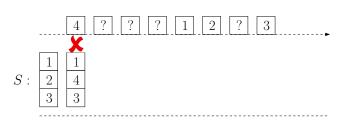
- Prove that the reasonable strategy is "safe" (key)
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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. There is an optimum solution in which p^* is evicted at time 1.

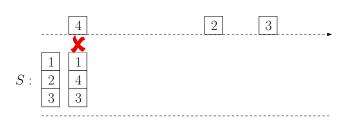
4 ? ? ? 1 2 ? 3

 $S: \begin{bmatrix} 1\\2\\3 \end{bmatrix}$

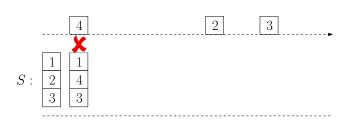
- $oldsymbol{0}$ S: any optimum solution
- p^* : page in cache not requested until furthest in the future.
 - In the example, $p^* = 3$.



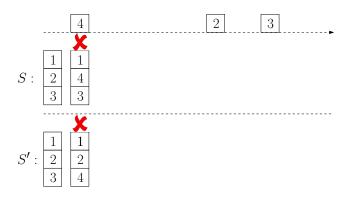
- - In the example, $p^* = 3$.
- **3** Assume S evicts some $p' \neq p^*$ at time 1; otherwise done.
 - In the example, p'=2.



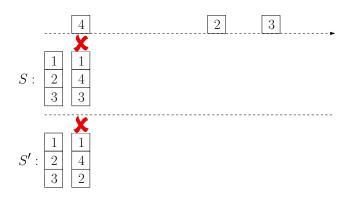
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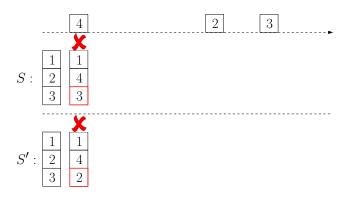
Proof.		



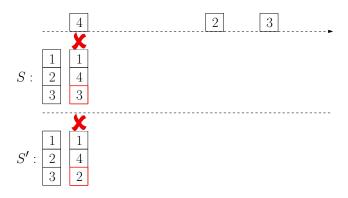
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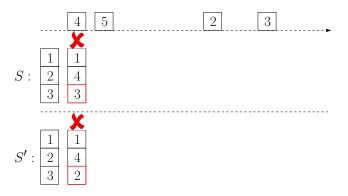
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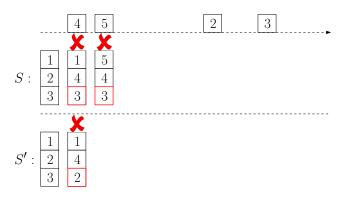
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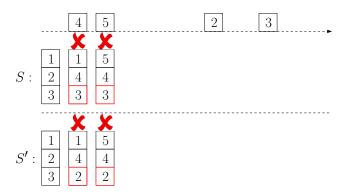
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- **1** From now on, S' will "copy" S.



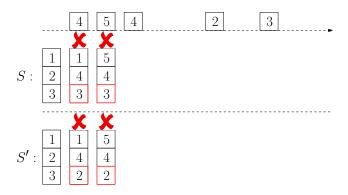
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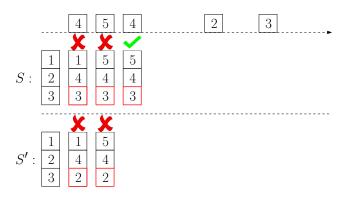
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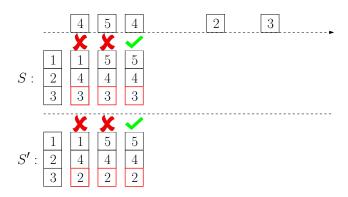
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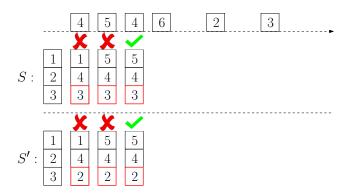
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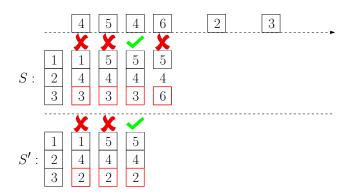
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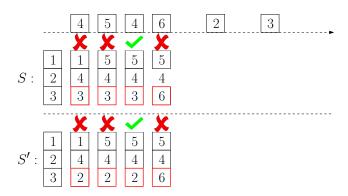
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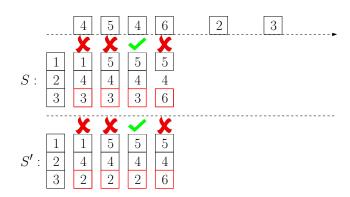
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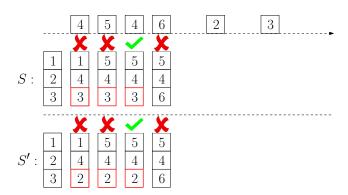


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- After time 1, cache status of S and that of S' differ by only 1 page. S' contains p'(=2) and S contains $p^*(=3)$.
- **1** From now on, S' will "copy" S.

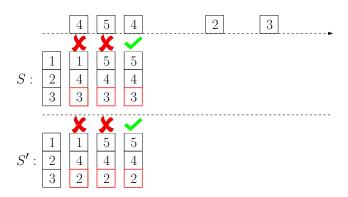


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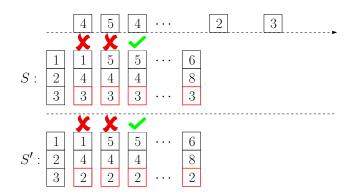




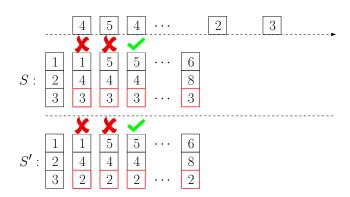
• If S evicted the page p^* , S' will evict the page p'. Then, the cache status of S and that of S' will be the same. S and S' will be exactly the same from now on.

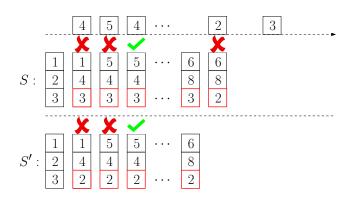


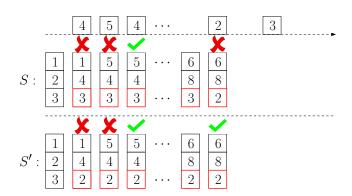
- If S evicted the page p^* , S' will evict the page p'. Then, the cache status of S and that of S' will be the same. S and S' will be exactly the same from now on.
- **3** Assume S did not evict $p^*(=3)$ before we see p'(=2).

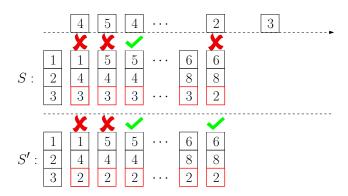


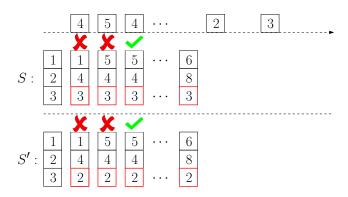
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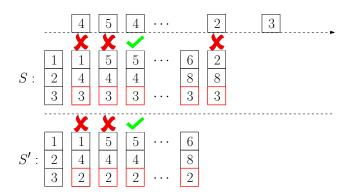


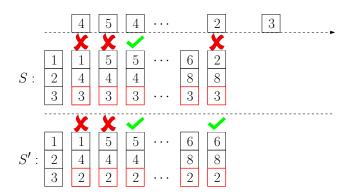


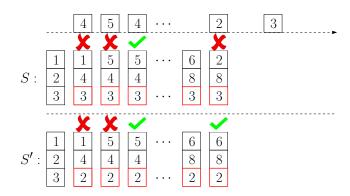




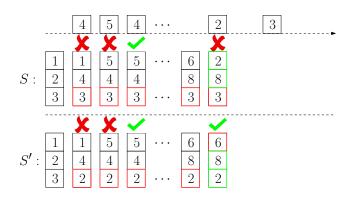




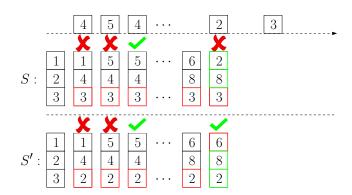


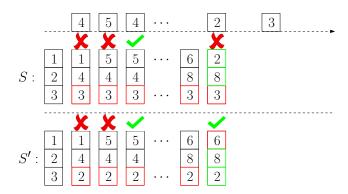


- **1** If S evicts $p^*(=3)$ for p'(=2), then S won't be optimum. Assume otherwise.
- $oldsymbol{0}$ So far, S' has 1 less page-miss than S does.

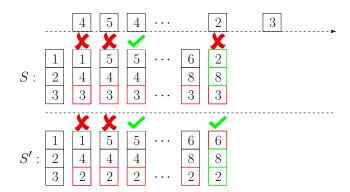


- **9** If S evicts $p^*(=3)$ for p'(=2), then S won't be optimum. Assume otherwise.
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- f 0 The status of S' and that of S only differ by f 1 page.





 $\ensuremath{\mathbf{@}}$ We can then guarantee that S' make at most the same number of page-misses as S does.



- We can then guarantee that S' make at most the same number of page-misses as S does.
 - Idea: if S has a page-hit and S' has a page-miss, we use the opportunity to make the status of S' the same as that of S.

 \bullet Thus, we have shown how to create another solution S' with the same number of page-misses as that of the optimum solution S. Thus, we proved

Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. There is an optimum solution in which p^* is evicted at time 1.

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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. It is safe to evict p^* at time 1.

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Lemma Assume at time 1 a page fault happens and there are no empty pages in the cache. Let p^* be the page in cache that is not requested until furthest in the future. It is safe to evict p^* at time 1.

Theorem The furthest-in-future strategy is optimum.

```
1: for t \leftarrow 1 to T do
2: if \rho_t is in cache then do nothing
3: else if there is an empty page in cache then
4: evict the empty page and load \rho_t in cache
5: else
6: p^* \leftarrow page in cache that is not used furthest in the future evict p^* and load \rho_t in cache
```

A:

• The running time can be made to be $O(n + T \log k)$.

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- For each page p, use a linked list (or an array with dynamic size) to store the time steps in which p is requested.
 - We can find the next time a page is requested easily.
- Use a priority queue data structure to hold all the pages in cache, so that we can easily find the page that is requested furthest in the future.

time	0	1	2	3	4	5	6	7	8	9	10	11	12	
pages		P1	P5	P4	P2	P5	Р3	P2	P4	Р3	P1	P5	Р3	

P1: | 1 | 10

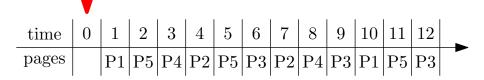
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values



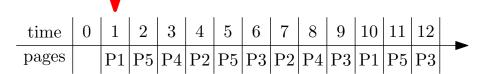
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values



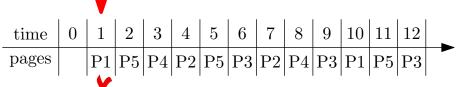
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values





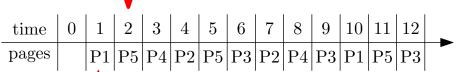
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values		
P1	10		





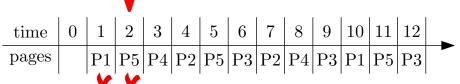
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values		
P1	10		





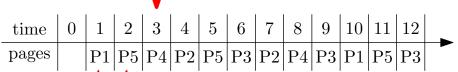
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P1	10
P5	5





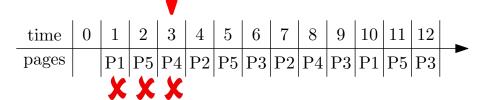
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P1	10
P5	5



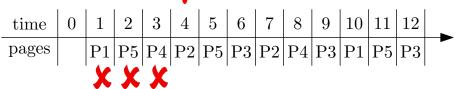
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P1	10
P5	5
P4	8



P1:

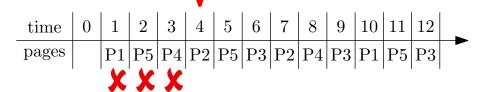
P2:

P3:

P4:

P5:

pages	priority values
P1	10
P5	5
P4	8



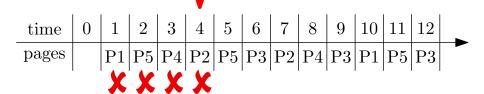
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P5	5
P4	8



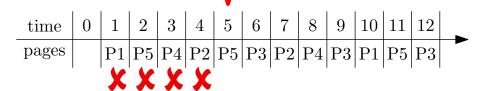
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	7
P5	5
P4	8



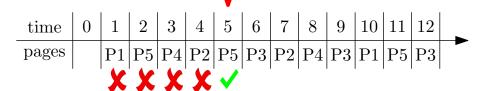
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	7
P5	5
P4	8



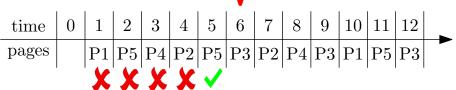
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	7
P5	11
P4	8



P1:

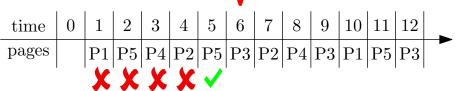
P2:

P3:

P4:

P5:

pages	priority values
P2	7
P5	11
P4	8



P1:

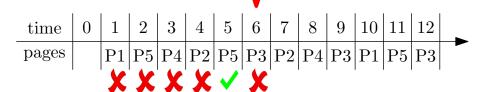
P2:

P3:

P4:

P5:

pages	priority values
P2	7
P4	8



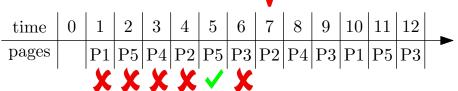
P2: 4 7

P3: | 6 | 9 | 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	7
Р3	9
P4	8



P1:

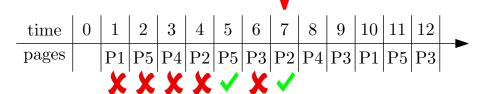
P2:

P3:

P4:

P5:

pages	priority values
P2	7
Р3	9
P4	8



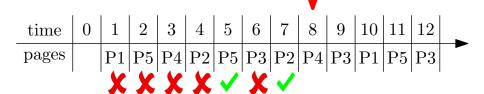
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	∞
Р3	9
P4	8



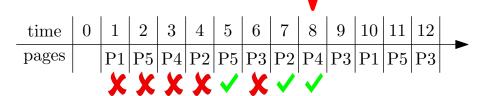
P2: 4 7

P3: 6 9 12

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P5: 2 5 11

pages	priority values
P2	∞
Р3	9
P4	8



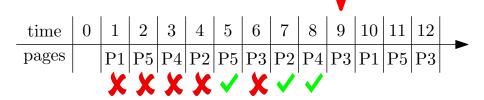
P2: 4 7

P3: | 6 | 9 | 12

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P5: 2 5 11

pages	priority values
P2	∞
Р3	9
P4	∞



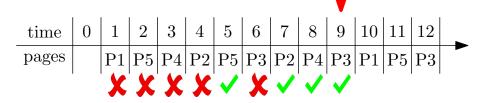
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	∞
Р3	9
P4	∞



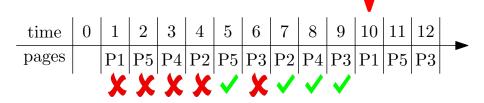
P2: 4 7

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P5: 2 5 11

pages	priority values
P2	∞
Р3	12
P4	∞



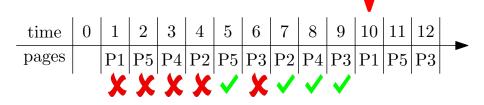
P2: 4 7

P3: | 6 | 9 | 12

P4: 3 8

P5: 2 5 11

pages	priority values
P2	∞
Р3	12
P4	∞



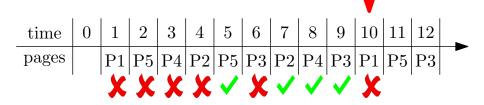
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
Р3	12
P4	∞



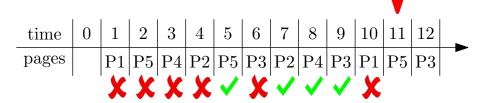
P2: 4 7

P3: 6 9 12

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P5: 2 5 11

pages	priority values
P1	∞
Р3	12
P4	∞



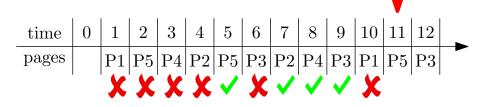
P2: 4 7

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P4: 3 8

P5: 2 5 11

pages	priority values
P1	∞
Р3	12
P4	∞



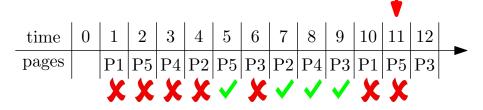
P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
Р3	12
P4	∞



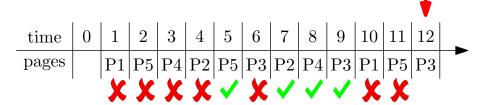
P2: 4 7

P3: | 6 | 9 | 12

P4: 3 8

P5: 2 5 11

pages	priority values
P5	∞
Р3	12
P4	∞



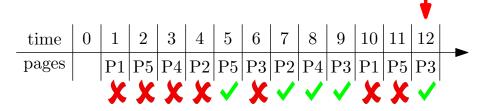
P2: 4 7

P3: 6 9 12

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P5: 2 5 11

pages	priority values
P5	∞
Р3	12
P4	∞



P2: 4 7

P3: 6 9 12

P4: 3 8

P5: 2 5 11

pages	priority values
P5	∞
Р3	∞
P4	∞

- 1: **for** every $p \leftarrow 1$ to n **do**
- 2: $times[p] \leftarrow \text{array of times in which } p \text{ is requested, in}$ increasing order $\qquad \qquad \triangleright \text{ put } \infty \text{ at the end of array}$
- 3: $pointer[p] \leftarrow 1$
- 4: $Q \leftarrow$ empty priority queue
- 5: **for** every $t \leftarrow 1$ to T **do**6: $pointer[\rho_t] \leftarrow pointer[\rho_t] + 1$
- 7: if $a \in O$ then
- 7: if $\rho_t \in Q$ then
- 8: $Q.\mathsf{increase-key}(\rho_t, times[\rho_t, pointer[\rho_t]])$, **print** "hit",

continue

- 9: **if** Q.size() < k **then**
- 10: **print** "load ρ_t to an empty page"
- 11: **else**
- 12: $p \leftarrow Q.\text{extract-max}(), \text{ print "evict } p \text{ and load } \rho_t$ "
- 13: $Q.\mathsf{insert}(\rho_t, times[\rho_t, pointer[\rho_t]])
 ightharpoonup \mathsf{add} \ \rho_t \ \mathsf{to} \ Q \ \mathsf{with} \ \mathsf{key}$ value $times[\rho_t, pointer[\rho_t]]$

Outline

- Toy Example: Box Packing
- 2 Interval Scheduling
- Scheduling to Minimize Lateness
- Weighted Completion Time Scheduling
- Offline Caching
 - Heap: Concrete Data Structure for Priority Queue
- 6 Data Compression and Huffman Code
- Summary

• Let V be a ground set of size n.

Def. A priority queue is an abstract data structure that maintains a set $U \subseteq V$ of elements, each with an associated key value, and supports the following operations:

- insert (v, key_value) : insert an element $v \in V \setminus U$, with associated key value key_value .
- \bullet decrease_key(v, new_key_value): decrease the key value of an element $v \in U$ to new_key_value
- \bullet extract_min(): return and remove the element in U with the smallest key value
- <u>。 . . .</u>

data structures	insert	extract_min	decrease_key
array			
sorted array			

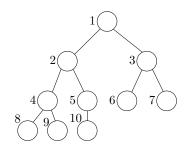
data structures	insert	extract_min	decrease_key
array	O(1)	O(n)	O(1)
sorted array			

data structures	insert	extract_min	decrease_key
array	O(1)	O(n)	O(1)
sorted array	O(n)	O(1)	O(n)

data structures	insert	extract_min	decrease_key
array	O(1)	O(n)	O(1)
sorted array	O(n)	O(1)	O(n)
heap	$O(\lg n)$	$O(\lg n)$	$O(\lg n)$

Heap

The elements in a heap is organized using a complete binary tree:

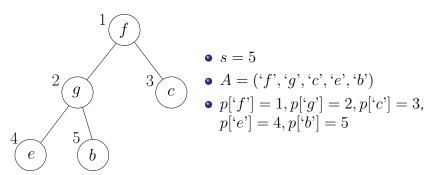


- Nodes are indexed as $\{1, 2, 3, \cdots, s\}$
- Parent of node i: $\lfloor i/2 \rfloor$
- Left child of node i: 2i
- Right child of node i: 2i + 1

Heap

A heap H contains the following fields

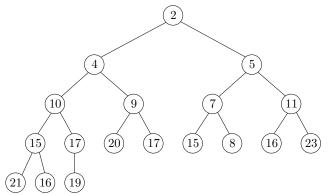
- s: size of U (number of elements in the heap)
- $A[i], 1 \le i \le s$: the element at node i of the tree
- $p[v], v \in U$: the index of node containing v
- $key[v], v \in U$: the key value of element v



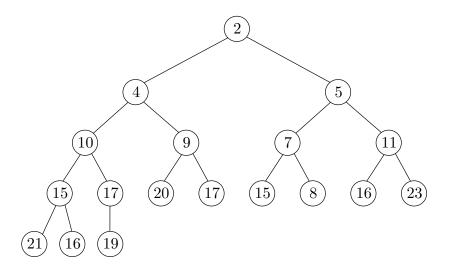
Heap

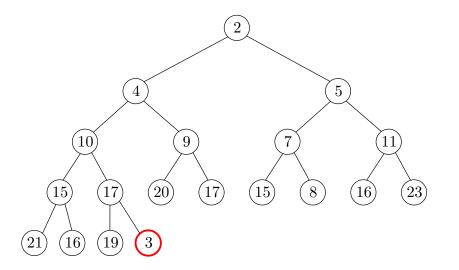
The following heap property is satisfied:

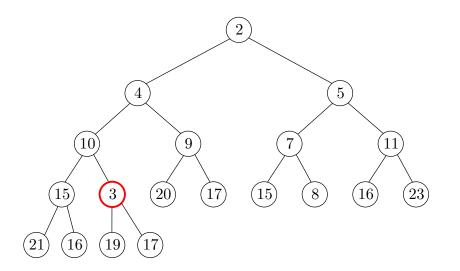
• for any two nodes i, j such that i is the parent of j, we have $key[A[i]] \le key[A[j]]$.

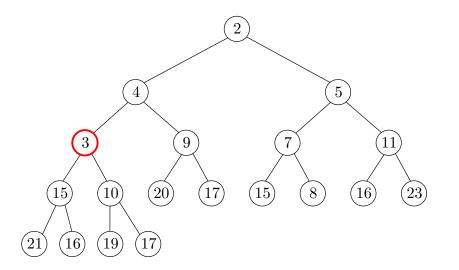


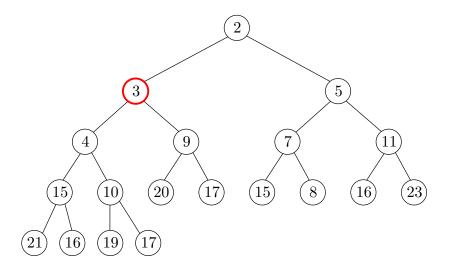
A heap. Numbers in the circles denote key values of elements.









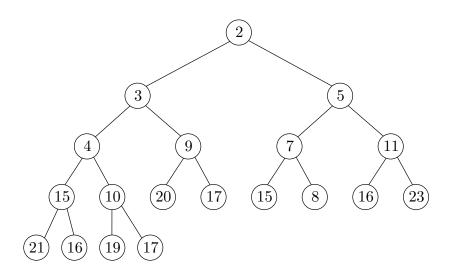


- 1: $s \leftarrow s + 1$ 2: $A[s] \leftarrow v$
- 3: $p[v] \leftarrow s$
- 4: $key[v] \leftarrow key_value$
- 5: heapify_up(s)

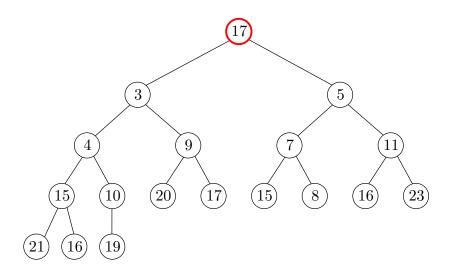
heapify-up(i)

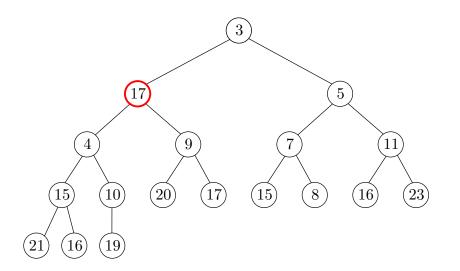
- 1: **while** i > 1 **do**
 - $j \leftarrow \lfloor i/2 \rfloor$
- 3: if key[A[i]] < key[A[j]] then
- 4: swap A[i] and A[j]
- 5: $p[A[i]] \leftarrow i, p[A[j]] \leftarrow j$
- 6: $i \leftarrow j$
- 7: **else** break

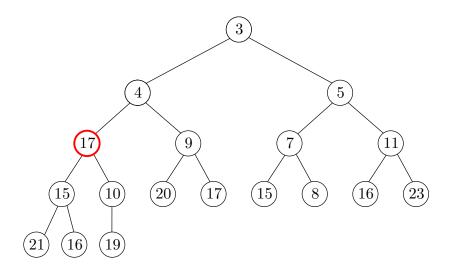
extract_min()

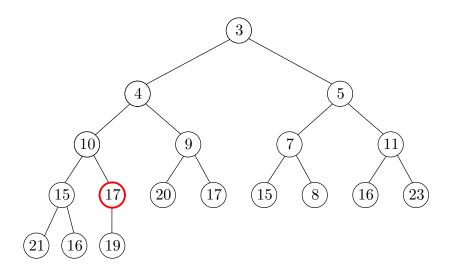


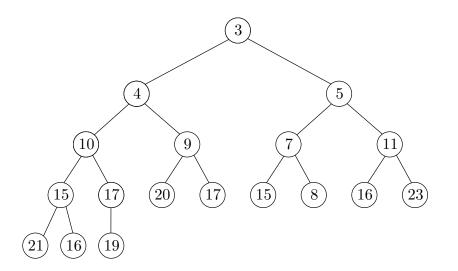
extract_min()











- 1: $ret \leftarrow A[1]$
- 2: $A[1] \leftarrow A[s]$
- 3: $p[A[1]] \leftarrow 1$
- 4: $s \leftarrow s 1$
- 5: **if** s > 1 **then**
- 6: $heapify_down(1)$
- 7: return ret

$decrease_key(v, key_val)$

- 1: $key[v] \leftarrow key_value$
- 2: heapify-up(p[v])

heapify-down(i)

- 1: while $2i \leq s$ do
- if 2i = s or

 $key[A[2i]] \le key[A[2i+1]]$ then

- $i \leftarrow 2i$ 3:
- else 4:
- $i \leftarrow 2i + 1$ 5:
- if key[A[j]] < key[A[i]] then 6:
- swap A[i] and A[j]7:
- $p[A[i]] \leftarrow i, p[A[i]] \leftarrow i$ 8: $i \leftarrow j$
- 9:
- else break 10:

 \bullet Running time of heapify_up and heapify_down: $O(\lg n)$

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data structures	insert	extract_min	decrease_key
array	O(1)	O(n)	O(1)
sorted array	O(n)	O(1)	O(n)
heap	$O(\lg n)$	$O(\lg n)$	$O(\lg n)$

Two Definitions Needed to Prove that the Procedures Maintain Heap Property

Def. We say that H is almost a heap except that key[A[i]] is too small if we can increase key[A[i]] to make H a heap.

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Outline

- Toy Example: Box Packing
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Encoding Letters Using Bits

- 8 letters a, b, c, d, e, f, g, h in a language
- need to encode a message using bits
- idea: use 3 bits per letter

$$deacfg \rightarrow 0111000000101011110$$

Q: Can we have a better encoding scheme?

Seems unlikely: must use 3 bits per letter

Q: What if some letters appear more frequently than the others?

Q: If some letters appear more frequently than the others, can we have a better encoding scheme?

A: Using variable-length encoding scheme might be more efficient.

Idea

• using fewer bits for letters that are more frequently used, and more bits for letters that are less frequently used.

Q: What is the issue with the following encoding scheme?

a: 0 *b*: 1 *c*: 00

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• a: 0 b: 1 c: 00

A: Can not guarantee a unique decoding. For example, 00 can be decoded to aa or c.

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• a: 0 b: 1 c: 00

A: Can not guarantee a unique decoding. For example, 00 can be decoded to aa or c.

Solution

Use prefix codes to guarantee a unique decoding.

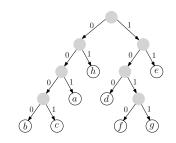
Prefix Codes

Def. A prefix code for a set S of letters is a function $\gamma:S\to\{0,1\}^*$ such that for two distinct $x,y\in S$, $\gamma(x)$ is not a prefix of $\gamma(y)$.

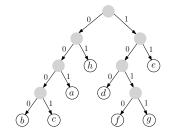
Prefix Codes

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a	b	c	$\mid d \mid$
001	0000	0001	100
\overline{e}	f	g	h
11	1010	1011	01

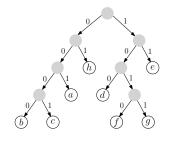


a	b	c	d
001	0000	0001	100
\overline{e}	f	g	h



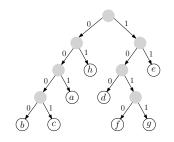
• Reason: there is only one way to cut the first code.

a	b	c	$\mid d \mid$
001	0000	0001	100
e	f	g	h



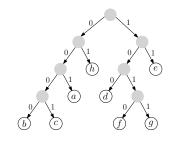
• 0001001100000001011110100001001

a	$\mid b \mid$	c	$\mid d \mid$
001	0000	0001	100
\overline{e}	f	g	h



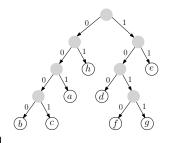
- 0001/001100000001011110100001001
- (

a	b	c	d
001	0000	0001	100
	ſ		1
e	J	g	$\mid n \mid$



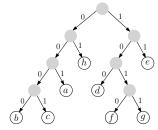
- 0001/001/100000001011110100001001
- ca

a	b	c	d
001	0000	0001	100
e	f	g	h



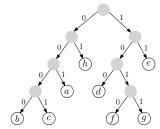
- 0001/001/100/000001011110100001001
- cad

a	b	c	d
001	0000	0001	100
	ſ		1
e	J	g	$\mid n \mid$



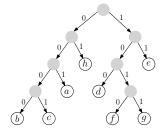
- 0001/001/100/0000/01011110100001001
- cadb

a	b	c	d
001	0000	0001	100
	ſ		1
e	J	g	$\mid n \mid$



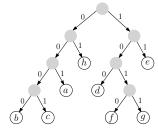
- 0001/001/100/0000/<mark>01</mark>/011110100001001
- cadbh

a	b	c	d
001	0000	0001	100
e	$\mid f \mid$	g	h



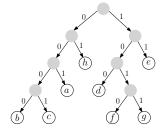
- 0001/001/100/0000/01/<mark>01</mark>/1110100001001
- cadbhh

a	b	c	d
001	0000	0001	100
e	$\mid f \mid$	g	h



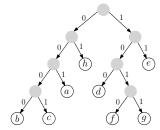
- 0001/001/100/0000/01/01/11/10100001001
- cadbhhe

a	b	c	d
001	0000	0001	100
e	$\mid f \mid$	g	h



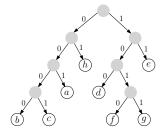
- 0001/001/100/0000/01/01/11/<mark>1010</mark>/0001001
- cadbhhef

a	b	c	d
001	0000	0001	100
e	$\mid f \mid$	g	h

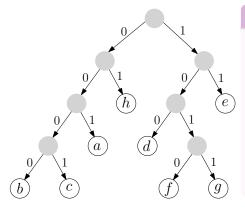


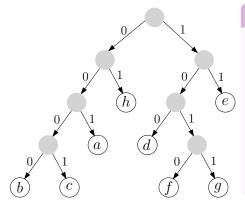
- 0001/001/100/0000/01/01/11/1010/0001/001
- cadbhhefc

a	b	c	d
001	0000	0001	100
e	f	g	$\mid h \mid$

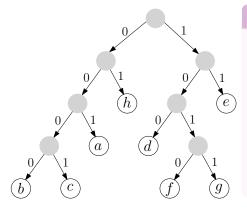


- 0001/001/100/0000/01/01/11/1010/0001/<mark>001</mark>/
- cadbhhefca

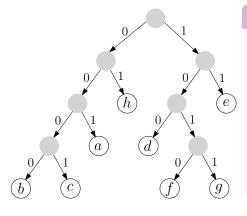




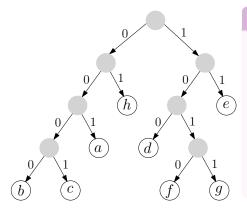
Rooted binary tree



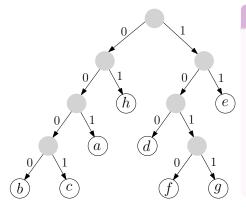
- Rooted binary tree
- Left edges labelled 0 and right edges labelled 1



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Best Prefix Codes

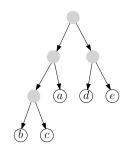
Input: frequencies of letters in a message

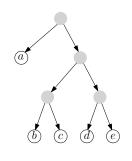
Output: prefix coding scheme with the shortest encoding for the

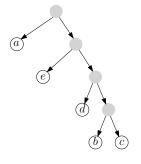
message

example

letters	a	b	c	$\mid d \mid$	$\mid e \mid$	
frequencies	18	3	4	6	10	







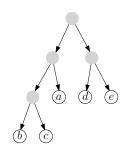
scheme 1

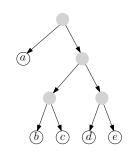
scheme 2

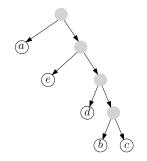
scheme 3

example

letters	$\mid a \mid$	b	c	d	$\mid e \mid$	
frequencies	18	3	4	6	10	
scheme 1 length	2	3	3	2	2	total = 89
scheme 2 length	1	3	3	3	3	total = 87
scheme 3 length	1	4	4	3	2	total = 84







scheme 1 scheme 2

scheme 3

Q: What types of decisions should we make?

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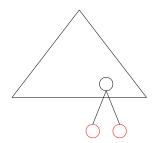
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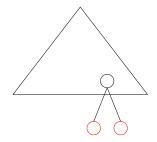
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- Not clear how to design the greedy algorithm

A: We can choose two letters and make them brothers in the tree.

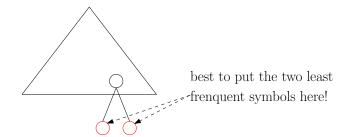
• Focus on the "structure" of the optimum encoding tree



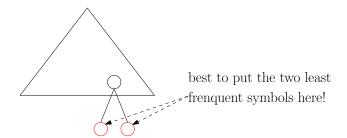
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Lemma It is safe to make the two least frequent letters brothers.

 So we can irrevocably decide to make the two least frequent letters brothers.

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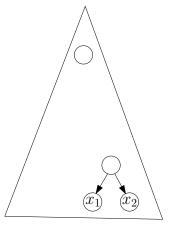
Q: Is the residual problem another instance of the best prefix codes problem?

 So we can irrevocably decide to make the two least frequent letters brothers.

 $\boldsymbol{\mathsf{Q}}\boldsymbol{:}\;$ Is the residual problem another instance of the best prefix codes problem?

A: Yes, though it is not immediate to see why.

- f_x : the frequency of the letter x in the support.
- x_1 and x_2 : the two letters we decided to put together.
- ullet d_x the depth of letter x in our output encoding tree.

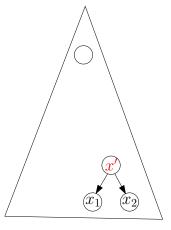


$$\sum_{x \in S} f_x d_x$$

$$= \sum_{x \in S \setminus \{x_1, x_2\}} f_x d_x + f_{x_1} d_{x_1} + f_{x_2} d_{x_2}$$

$$= \sum_{x \in S \setminus \{x_1, x_2\}} f_x d_x + (f_{x_1} + f_{x_2}) d_{x_1}$$

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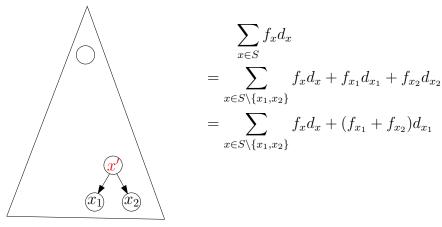


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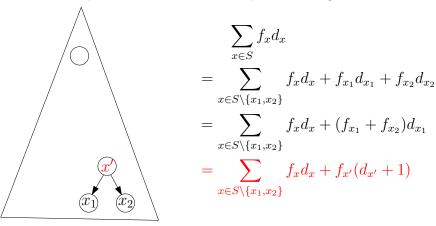
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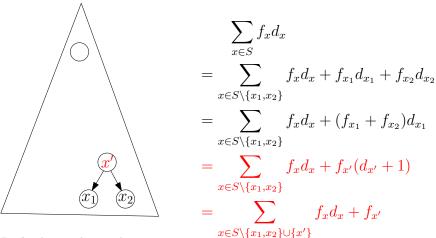
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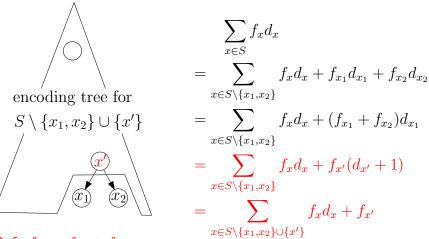
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In order to minimize

$$\sum_{x \in S} f_x d_x,$$

we need to minimize

$$\sum_{x \in S \setminus \{x_1, x_2\} \cup \{x'\}} f_x d_x,$$

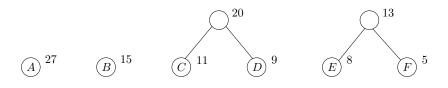
subject to that d is the depth function for an encoding tree of $S \setminus \{x_1, x_2\}$.

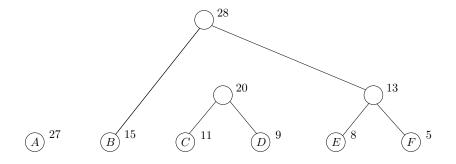
• This is exactly the best prefix codes problem, with letters $S \setminus \{x_1, x_2\} \cup \{x'\}$ and frequency vector f!

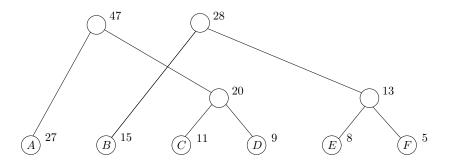


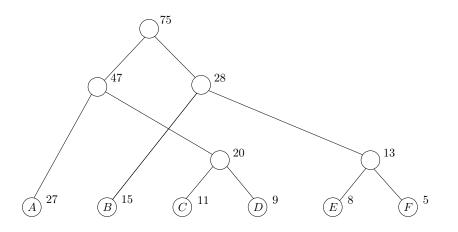
 $\bigcirc D$ 9

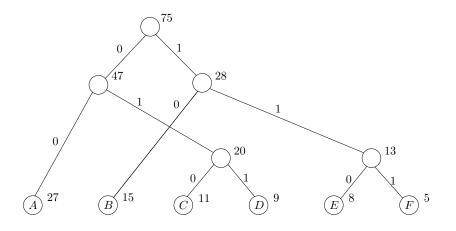


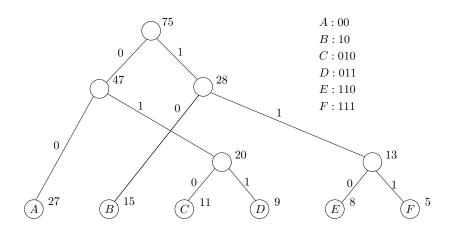












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$\mathsf{Huffman}(S,f)$

- 1: while |S| > 1 do
- 2: let x_1, x_2 be the two letters with the smallest f values
- 3: introduce a new letter x' and let $f_{x'} = f_{x_1} + f_{x_2}$
- 4: let x_1 and x_2 be the two children of x'
- 5: $S \leftarrow S \setminus \{x_1, x_2\} \cup \{x'\}$
- 6: **return** the tree constructed

Algorithm using Priority Queue

```
Huffman(S, f)

1: Q \leftarrow \text{build-priority-queue}(S)

2: while Q.\text{size} > 1 do

3: x_1 \leftarrow Q.\text{extract-min}()

4: x_2 \leftarrow Q.\text{extract-min}()

5: introduce a new letter x' and let f_{x'} = f_{x_1} + f_{x_2}

6: let x_1 and x_2 be the two children of x'

7: Q.\text{insert}(x', f_{x'})

8: return the tree constructed
```

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- Show that the remaining task after applying the strategy is to solve a (many) smaller instance(s) of the same problem (usually easy)

A Common Way to Analyze Greedy Algorithms

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Def. A strategy is "safe" if there is always an optimum solution that "agrees with" the decision made according to the strategy.

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 - Offline caching: a complicated "copying" algorithm
 - Huffman codes: move the two least frequent letters to the deepest leaves.

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- Two problems that do not fall into the category: lateness, weighted completion time