# Advanced Algorithms (Fall 2025) Multiplicative Weight Update

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- Focus of this lecture: learning with experts online
- how to dynamically choose from among a set of "experts" in a way that compares favorably to the best expert
- Use it to solve 0-sum game and linear programs approximately

- Online Learning with Experts
  - Two-outcome case
  - A more general setting
- Multiplicative Weight Update Algorithm to Solve 0-Sum Game
- 3 Approximate LP feasibility using Multiplicative Weights

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#### Learning with Experts Online

- m experts, indexed by [m]
- ullet a two-outcome event on each of following T days: up or down
  - Example: stock goes up or down? rain or not?
- on each day t:
  - ullet m experts make predictions about day t
  - ullet algorithm makes a prediction, knowing the predictions of the m experts
  - ullet the outcome of day t reveals
- Goal: minimize the number of mistakes
  - Ideally, not too bad compared to the best expert.

# When There Is a Perfect Expert

**Lemma** There is an algorithm that makes at most  $\lceil \log_2 m \rceil$  mistakes, assuming there is a perfect expert, i.e., an expert that makes no mistakes.

#### Proof.

- The algorithm: only keep the experts who made no mistakes so far.
- Among all the experts, follow the majority.
- observation: when we made a mistake on a day, at least half of the remaining experts made a mistake on that day.

## General Case

- What if there is no perfect expert?
- Weighted majority: give weights to experts. When an expert made a mistake, halve his weight. In each step, follow the weighted majority.

## Weighted Majority

## **Analysis**

- $\bullet \ \Phi^t := \sum_{i=1}^m w_i^t.$
- $M_i^t \in \{0,1\}, i \in [m], t \in [T]$ : whether expert i made a mistake on day t
- ullet  $M^t \in \{0,1\}, t \in [T]$ : whether our algorithm made a mistake

**Obs.** If  $M^t = 1$  for some t, we have

$$\Phi^t \le \Phi^{t-1} - \frac{\Phi^{t-1}}{4} = \frac{3}{4}\Phi^{t-1}$$

- So,  $\Phi^T \leq (\frac{3}{4})^{\sum_{t=1}^T M^t} \Phi_0 = (\frac{3}{4})^{\sum_{t=1}^T M^t} m$ .
- On the other hand, let k be the best expert

$$\Phi^{T} = \sum_{i=1}^{m} w_{i}^{T} \ge w_{k}^{T} \ge \left(\frac{1}{2}\right)^{\sum_{t=1}^{T} M_{k}^{t}}$$

$$\Phi^T \le \left(\frac{3}{4}\right)^{\sum_{t=1}^T M^t} m \qquad \Phi^T \ge \left(\frac{1}{2}\right)^{\sum_{i=1}^T M_k^t}$$

$$\begin{split} \left(\frac{1}{2}\right)^{\sum_{i=1}^{T} M_i^t} & \leq \Phi^T \leq \left(\frac{3}{4}\right)^{\sum_{i=1}^{T} M^t} m \\ & (-\ln 2) \sum_{t=1}^{T} M_i^t \leq (-\ln \frac{4}{3}) \sum_{t=1}^{T} M^t + \ln m \quad \text{By taking logarithm} \\ & \sum_{t=1}^{T} M^t \leq \frac{\ln 2}{\ln 4/3} \sum_{t=1}^{T} M_k^t + \frac{\ln m}{\ln 4/3} \\ & \leq 2.41 \sum_{t=1}^{T} M_k^t + 3.47 \ln m \end{split}$$

$$\sum_{t=1}^{T} M^{t} \le 2.41 \sum_{t=1}^{T} M_{k}^{t} + 3.47 \ln m$$

## Make the first constant arbitrarily close to 2

- when expert i makes a mistake on day t:  $w_i^t \leftarrow w_i^{t-1} \cdot (1-\epsilon)$
- ullet when algorithm makes a mistake on day  $t\colon \Phi^t \leq \Phi^{t-1} \cdot (1-\frac{\epsilon}{2})$

$$\Phi_T \le (1 - \epsilon/2)^{\sum_{t=1}^T M^t} \cdot m$$

 $\bullet \ \Phi_T \ge (1 - \epsilon)^{\sum_{t=1}^T M_k^t}$ 

$$\sum_{t=1}^{T} M^{t} \le \frac{\ln(1-\epsilon)}{\ln(1-\epsilon/2)} \sum_{t=1}^{T} M_{k}^{t} - \frac{\ln m}{\ln(1-\epsilon/2)}$$
$$= (2+O(\epsilon)) \sum_{t=1}^{T} M_{k}^{t} + O\left(\frac{1}{\epsilon}\right) \ln m.$$

**Lemma** For any constant  $\epsilon>0$  and any function f(m), no deterministic algorithm can achieve a multiplicative factor of  $2-\epsilon$  and additive factor of f(m).

#### Proof.

- ullet Each day  $\frac{m}{2}$  experts predict "up",  $\frac{m}{2}$  experts predict "down".
- Our algorithm always makes a mistake.
- ullet Our algorithm made T mistakes, and the best expert makes at most T/2.

• If 
$$T \gg f(m)$$
, we have  $T > (2 - \epsilon) \cdot \frac{T}{2} + f(m)$ .

• However, if randomness is allowed, we can make multiplicative factor  $1+\epsilon$ .

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### A more general setting

- no predictions: experts pay penalties
- algorithm chooses to follow experts
- with randomness: follow a distribution over experts
- algorithm pays the weighted average penalty of experts
- goal: compare to the best expert

#### The General Setting

- 1: for  $t \leftarrow 1, 2, \cdots, T$  do
- 2: algorithm chooses a distribution  $p^t = (p_1^t, p_2^t, \cdots, p_n^t)$  over experts
- 3: the penalty vector  $M^t \in [-1, 1]^m$  is revealed
- 4: each expert i pays penalty  $M_i^t$
- 5: algorithm pays penalty  $\langle p^t, M^t \rangle = \sum_{i=1}^m p_i^t M_i^t$
- Note: penalty can be negative: negative penalty = reward

**Theorem** Let  $\epsilon \in (0,1]$ . If  $T \ge \frac{\ln m}{\epsilon^2}$ , then there is an algorithm that satisfies:

$$\frac{1}{T} \sum_{t=1}^{T} \langle p^t, M^t \rangle \le \frac{1}{T} \sum_{t=1}^{T} M_i^t + 2\epsilon, \forall i \in [m].$$

#### Algorithm for the General Setting

- 1:  $w_i^0 \leftarrow 1$  for every  $i \in [m]$
- 2: for  $t \leftarrow 1, 2, \cdots, T$  do
- 3: choose  $p^t \leftarrow \frac{w^{t-1}}{|w^{t-1}|_1}$
- 4: the penalty vector  $M^t \in [-1,1]^m$  is revealed
- 5: each expert i pays penalty  $M_i^t$
- 6: algorithm pays penalty  $\langle p^t, M^t \rangle = \sum_{i=1}^m p_i^t M_i^t$
- 7: **for** every  $i \in [m]$  **do**:  $w_i^t \leftarrow w_i^{t-1} \cdot e^{-\epsilon \cdot M_i^t}$

# Analysis of Algorithm

- $w_i^t = w_i^{t-1} \cdot e^{-\epsilon \cdot M_i^t}$ • the strategy:  $p^t = \frac{w^{t-1}}{|w^{t-1}|_1}$
- let  $\Phi^t := |w^t|_1 = \sum_{i=1}^m w_i^t$  for all  $t \in [0, T]$

$$\Phi^{t} = \sum_{i=1}^{m} w_{i}^{t} = \sum_{i=1}^{m} e^{-\epsilon \cdot M_{i}^{t}} \cdot w_{i}^{t-1}$$

$$\leq \sum_{i=1}^m (1-\epsilon\cdot M_i^t + (\epsilon\cdot M_i^t)^2)\cdot w_i^{t-1}$$
 as  $e^x \leq 1+x+x^2, \forall x \in [-1,1]$ 

$$i=1$$
 as  $e^x \leq \sum_{i=1}^m (1-\epsilon \cdot M_i^t + \epsilon^2) \cdot w_i^{t-1}$ 

$$= (1 + \epsilon^2) \sum_{i=1}^{m} w_i^{t-1} - \epsilon \cdot \langle w^{t-1}, M^t \rangle$$

$$= (1 + \epsilon^2) \sum_{i=1}^{m} w_i^{t-1} - \epsilon \cdot \langle w^{t-1}, M^t \rangle$$
$$= (1 + \epsilon^2) \Phi^{t-1} - \epsilon \cdot \Phi^{t-1} \cdot \langle p^t, M^t \rangle$$

as  $\Phi^{t-1} \cdot p^t = w^{t-1}$ 

as  $|M_{i}^{t}| < 1$ 

# Analysis of Algorithm

$$\begin{split} \Phi^t & \leq (1+\epsilon^2) \Phi^{t-1} - \epsilon \cdot \Phi^{t-1} \cdot \langle p^t, M^t \rangle \\ & = \left(1+\epsilon^2 - \epsilon \cdot \langle p^t, M^t \rangle \right) \cdot \Phi^{t-1} \\ & \leq \exp\left(-\epsilon \cdot \langle p^t, M^t \rangle + \epsilon^2\right) \cdot \Phi^{t-1} \quad \text{ as } 1-x \leq e^{-x}, \forall x \in \mathbb{R} \end{split}$$

$$\Phi^{T} \leq \exp\left(\sum_{t=1}^{T} \left(-\epsilon \cdot \langle p^{t}, M^{t} \rangle + \epsilon^{2}\right)\right) \cdot \Phi^{0}$$
$$= \exp\left(-\epsilon \cdot \sum_{t=1}^{T} \langle p^{t}, M^{t} \rangle + T\epsilon^{2}\right) \cdot \Phi^{0}$$

$$\Phi^T \le \exp\left(-\epsilon \cdot \sum_{t=1}^T \langle p^t, M^t \rangle + T\epsilon^2\right) \cdot \Phi^0$$

- For any expert  $i \in [m]$ ,  $\Phi^T \ge w_i^T = \exp\Big(-\epsilon \sum_i M_i^t\Big)$ .
- So, for every  $i \in [m]$ , we have (note that  $\Phi^0 = m$ )

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$$i \in [m]$$
, we have (note that  $\Phi^0 = m$ )

- $-\epsilon \cdot \sum_{i=1}^{T} M_{i}^{t} \leq -\epsilon \cdot \sum_{i=1}^{T} \langle p^{t}, M^{t} \rangle + T\epsilon^{2} + \ln m$
- $\sum_{t=0}^{T} \langle p^{t}, M^{t} \rangle \leq \sum_{t=0}^{T} M_{i}^{t} + T\epsilon + \frac{\ln m}{\epsilon}$
- $\frac{1}{T} \sum_{t=0}^{T} \langle p^{t}, M^{t} \rangle \leq \frac{1}{T} \sum_{t=0}^{T} M_{i}^{t} + \epsilon + \frac{\ln m}{T\epsilon}$

$$\leq \frac{1}{T} \sum_{t=1}^{T} M_i^t + 2\epsilon \qquad \left[ T \geq \frac{\ln m}{\epsilon^2} \right]_{17/27}$$

**Theorem** Let  $\epsilon \in (0,1]$ . If  $T \ge \frac{\ln m}{\epsilon^2}$ , then there is an algorithm that satisfies:

$$\frac{1}{T} \sum_{t=0}^{T} \langle p^{t}, M^{t} \rangle \leq \frac{1}{T} \sum_{t=0}^{T} M_{i}^{t} + 2\epsilon, \forall i \in [m].$$

**Coro.** Suppose each penalty in the game is in  $[-\rho,\rho]$  (instead of [-1,1]) for some  $\rho>0$ . Let  $\epsilon\in \left(0,2\rho\right]$ . If  $T\geq \frac{4\rho^2\ln m}{\epsilon^2}$ , then there is an algorithm that satisfies

$$\frac{1}{T} \sum_{t=1}^{T} \langle p^t, M^t \rangle \leq \frac{1}{T} \sum_{t=1}^{T} M_i^t + \epsilon, \forall i \in [m].$$

## Proof.

- scale penalties by  $\frac{1}{a}$  so that each penalty is in [-1,1]
- $+\epsilon$  before scaling  $= +\frac{\epsilon}{a}$  after scaling
- Need  $T \geq \frac{\ln m}{(\epsilon/2\rho)^2} = \frac{4\rho^2 \ln m}{\epsilon^2}$  and  $\frac{\epsilon}{2\rho} \leq 1 \iff \epsilon \leq 2\rho$

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#### Recall:

#### 0-Sum Game

**Input:** a payoff matrix  $M \in \mathbb{R}^{m \times n}, m, n \ge 1$ ,

two players: row player R, column player C

**Output:** R plays a row  $i \in [m]$ , C plays a column  $j \in [n]$ 

payoff of game is  $M_{ij}$ 

R wants to minimize  $M_{ij}$ , C wants to maximize  $M_{ij}$ 

Rock-Scissor-Paper Game					
payoff	R	S	Р		
R	0	-1	1		
S	1	0	-1		
Р	-1	1	0		

• By scaling, we assume  $M \in [-1, 1]^{m \times n}$ .

player	objective	game term	number	distribution
row player	minimize	expert	m	y
column player	maximize	event	n	x

### Multiplicative weight update for 0-sum games

```
1: let w_i^0 = 1 for every i \in [m]
```

2: **for** 
$$t \leftarrow 1$$
 to  $T$ , where  $T = \left\lceil \frac{4 \ln m}{\epsilon^2} \right\rceil$  **do**

3: algorithm chooses distribution 
$$y^t = \frac{w^{t-1}}{|w^{t-1}|_1}$$

4: let 
$$j^t$$
 be the  $j \in [n]$  that maximizes  $M(y^t, j)$ 

5: event 
$$j^t$$
 happens:

expert 
$$i \in [m]$$
 pays penalty  $M(i, j_t)$  algorithm pays penalty  $M(y^t, j_t)$ 

6: 
$$w_i^t \leftarrow w_i^{t-1} \cdot e^{-\epsilon \cdot M(i,j_t)/2}$$
 for every  $i \in [m]$ 

player	objective	game term	number	distribution
row player	minimize	expert	m	y
column player	maximize	event	n	x

• Since  $T \geq \frac{4 \ln m}{\epsilon^2}$ , we have

$$\frac{1}{T} \sum_{t=1}^{T} M(p^t, j^t) \leq \min_{i \in [m]} \frac{1}{T} \sum_{t=1}^{T} M(i, j^t) + \epsilon$$

- $\hat{t}$ : the  $t \in [T]$  with minimum  $M(y^t, j^t)$
- $\hat{y} := y^t$ •  $\hat{x}$ : uniform distribution over multi-set  $\{j^1, j_2, \cdots, j^T\}$

• 
$$\hat{x}$$
: uniform distribution over multi-set  $\{j^1, j_2, \cdots, j^T\}$ 

$$\max_{j} M(\hat{y}, j) = M(\hat{y}, j^{\hat{t}}) \le \frac{1}{T} \sum_{t=1}^{T} M(p^{t}, j^{t})$$

$$\le \min_{i} \frac{1}{T} \sum_{t=1}^{T} M(i, j^{t}) + \epsilon = \min_{i} M(i, \hat{x}) + \epsilon$$

player	objective	game term	number	distribution
row player	minimize	expert	m	y
column player	maximize	event	n	x

$$\max_{j} M(\hat{y}, j) \le \min_{i} M(i, \hat{x}) + \epsilon$$

•  $\lambda^*$ : value of game

$$\lambda^* \le \max_{\hat{i}} M(\hat{y}, j) \le \min_{\hat{i}} M(i, \hat{x}) + \epsilon \le \lambda^* + \epsilon$$

• Therefore  $\hat{y}$  and  $\hat{x}$  are approximately the optimum strategies for the row and column players.

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#### Linear Program: Exact Version

**Input:** An "easy" polytope  $K \subseteq \mathbb{R}^n$  (e.g.,  $K = [0,1]^n$ ) normal linear constraints  $Ax \geq b$ ,  $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$ 

**Output:** decide if  $\{x \in K : Ax \ge b\} = \emptyset$ , if not, then output  $x \in K$  with  $Ax \ge b$ 

#### Linear Program: Approximate Version

**Input:** An "easy" polytope  $K \subseteq \mathbb{R}^n$  (e.g.,  $K = [0,1]^n$ ) normal linear constraints  $Ax \geq b$ ,  $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$ 

**Output:** either claim  $\{x \in K : Ax \ge b\} = \emptyset$ , or output  $x \in K$  with  $Ax \ge b - \epsilon \cdot \mathbf{1}$ 

 Note: in case there is no exact solution, but an approximate solution, algorithm can respond either way.

# Approximate LP Solver using MWU

$row \; of \; A$	constraint	expert	dual solution $\boldsymbol{y}$	m
column of $A$	variable		primal solution $\boldsymbol{x}$	$\overline{n}$

ullet event = a point in K

```
1: w_i^0 \leftarrow 1 for every i \in [m]
 2: for t \leftarrow 1 to T, for some T to be decided later do
           y^t \leftarrow \frac{w^{t-1}}{|w^{t-1}|}
 3:
        if \exists x^t \in K \text{ s.t } \langle y^t, Ax \rangle \geq \langle y^t, b \rangle then \triangleright event x^t happens
 4:
                 for every i \in [m] do
 5:
                       expert i gets penalty A_i x^t - b_i
 6:
                       w_i^t \leftarrow w_i^{t-1} \cdot e^{-\epsilon \cdot (A_i x^t - b_i)/2}
 7:
                 our algorithm gets penalty \langle y^t, Ax^t - b \rangle
 8:
            else return "empty"
 9:
10: return \hat{x} = \frac{1}{T} \sum_{i=1}^{T} x^{t}
```

- Counter-intuitive: the more satisfied a constraint is, the more penalty it gets.
- In every iteration, we only need to focus on one "aggregated" linear constraint
- If algorithm returns "empty", then the LP is not feasible

• 
$$\rho := \sup_{x \in K} \max_i |A_i x - b_i|, \quad \epsilon \in (0, 2\rho] \quad T := \left\lceil \frac{4\rho^2 \ln m}{\epsilon^2} \right\rceil$$

•  $\forall i \in [m]$ :

$$0 \le \frac{1}{T} \sum_{t=1}^{T} \langle y^t, Ax^t - b \rangle \le \frac{1}{T} \sum_{t=1}^{T} (A_i x^t - b_i) + \epsilon = A_i \hat{x} - b_i + \epsilon$$

• Therefore,  $A_i x^* > b_i - \epsilon, \forall i \in [m] \iff Ax^* > b - \epsilon \cdot \mathbf{1}$