

Advanced Algorithms (Fall 2025)

Semi-Definite Programming

Lecturers: 尹一通, 刘景铖, 栗师

Nanjing University

Outline

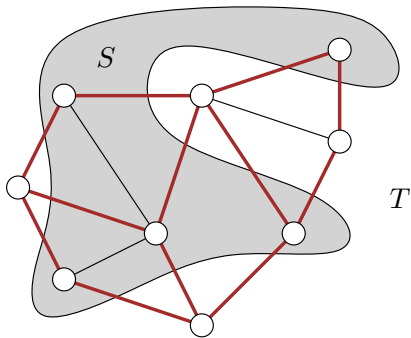
- 1 Max-Cut Problem
- 2 Semi-Definite Programming
- 3 0.878-Approximation for Max-Cut Using SDP
- 4 Duality for Semi-Definite Programming
- 5 Ellipsoid Method runs In Polynomial Time

Maximum Cut Problem

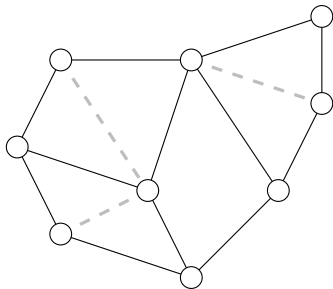
Input: $G = (V, E)$,

Output: a partition $(S \subseteq V, T := V \setminus S)$ of V so as to maximize $|E(S, T)|$,

where $E(S, T) = \{uv \in E : |\{u, v\} \cap S| = 1\}$



- **Min-Uncut:** remove minimum number of edges to make graph bipartite



- Max-Cut = Min-Uncut for exact algorithms, but not the same for approximation algorithms
- Recap: 1/2-approximation algorithms for Max-Cut:

Randomized Algorithm

```
1:  $S \leftarrow \emptyset$   
2: for every  $u \in V$  do  
3:   with probability  
   1/2, add  $u$  to  $S$   
4: return  $(S, V \setminus S)$ 
```

Greedy Algorithms

```
1:  $S \leftarrow \emptyset, T \leftarrow \emptyset$   
2: for every  $u \in V$  do  
3:   if  $|E(u, S)| > |E(u, T)|$  then  
4:      $T \leftarrow T \cup \{u\}$   
5:   else  
6:      $S \leftarrow S \cup \{u\}$   
7: return  $(S, T)$ 
```

- Local Search: while we can improve the solution by switching the side of one vertex, perform the operation, stop if no swapping can improve the solution

Linear Programming Relaxation

First Attempt

- $y_v, v \in V$: if $v \in S$
- $x_{uv}, uv \in E$: if uv is cut

$$\max \sum_{uv \in E} x_{uv}$$

$$\begin{aligned} x_{uv} &\leq |y_u - y_v| & \forall uv \in E \\ y_v &\in [0, 1] & \forall v \in V \end{aligned}$$

- $x_{uv} \leq |y_u - y_v|$ is not linear
- feasible region is not convex:

y_u	y_v	x_{uv}	Y/N
1	0	0.5	Y
0	1	0.5	Y
0.5	0.5	0.5	N

- $x_{uv} \geq |y_u - y_v|$ can be replaced by $x_{uv} \geq y_u - y_v$ and $x_{uv} \geq y_v - y_u$

Second Attempt

- $x_{uv}, uv \in \binom{V}{2}$: whether uv is cut

$$\min \sum_{u,v \in V, u < v} x_{uv}$$

$$x_{uv} + x_{vw} + x_{uw} \leq 2 \quad \forall u, v, w \in V$$

$$x_{uv} \in [0, 1] \quad \forall u, v \in V$$

- The **integrality gap** of the LP is $2 - \epsilon$: there is an instance, where $\text{opt} \approx |E|/2$ and $\text{lp} \approx |E|$

Quadratic Program

$$\bullet \ y_v = \begin{cases} 1 & \text{if } v \in S \\ -1 & \text{if } v \notin S \end{cases}$$

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{uv \in E} (1 - y_u y_v) \\ & y_v \in \{\pm 1\} \quad \forall v \in V \end{aligned}$$

Semi-Definite Program

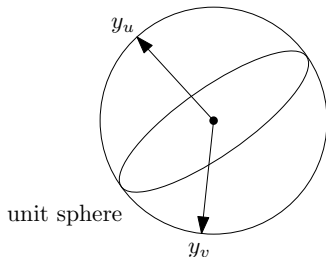
$$\bullet \ y_v \in \mathbb{R}^n, \forall v \in V$$

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{uv \in E} (1 - \langle y_u, y_v \rangle) \\ & |y_v| = 1 \quad \forall v \in V \end{aligned}$$

- $\bullet \ \langle y_u, y_v \rangle = y_u^T y_v = \sum_{i=1}^n y_{u,i} \cdot y_{v,i}$: inner product of y_u and y_v
- \bullet requiring $y_v \in \mathbb{R}^n$ is the same as requiring $y_v \in \mathbb{R}^{n'}$ for any $n' \geq n$

SDP for Max-Cut

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{uv \in E} (1 - \langle y_u, y_v \rangle) \\ & |y_v| = 1 \quad \forall v \in V \end{aligned}$$



- SDP is a **relaxation**:

$$y_v = \begin{cases} (1, 0, 0, 0, \dots, 0) & \text{if } v \in S \\ (-1, 0, 0, 0, \dots, 0) & \text{if } v \in T \end{cases}$$

- sdp: the value of the SDP, $\text{sdp} \geq \text{opt}$

Q: Can we solve the SDP?

A: Yes

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Def. A symmetric matrix $X \in \mathbb{R}^{n \times n}$ is Positive Semi-Definite (PSD) if $\forall y \in \mathbb{R}^n$, we have $y^T X y \geq 0$. Use $X \succeq 0$ to denote X is PSD.

- $X \succeq X'$ means $X - X' \succeq 0$.

Lemma The following statements are equivalent for a symmetric matrix $X \in \mathbb{R}^{n \times n}$:

- $X \succeq 0$
- All the n eigenvalues of X are non-negative
- $X = V^T V$ for some $V \in \mathbb{R}^{m \times n}, m \leq n$
- $X = \sum_{u=1}^n \lambda_u w_u w_u^T$ for some reals $\lambda_1, \lambda_2, \dots, \lambda_n \geq 0$ and **orthonormal** basis $\{w_u\}_{u \in [n]}$

Semi-definite Programming (SDP)

- matrices of size $n \times n \equiv$ **flattened** vectors of length n^2 :
 - Use \cdot as multiplication for flattened matrices,
 - $X \succeq 0$: view X as a matrix.
- $A \in \mathbb{R}^{m \times n^2}, b \in \mathbb{R}^m, c \in \mathbb{R}^{n^2}$
- Assume A_k 's and c are symmetric matrices of size $n \times n$

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$A \cdot X \geq b$$

$$X \succeq 0$$

An equivalent formulation

$$\min \quad \sum_{u,v \in [n]} c_{u,v} \cdot \langle y_u, y_v \rangle$$

$$\sum_{u,v} a_{k,u,v} \langle y_u, y_v \rangle \geq b_k \quad \forall k \in [m]$$

$$y_v \in \mathbb{R}^n \quad \forall v \in [n]$$

- requiring $y_v \in \mathbb{R}^n$ is the same as requiring $y_v \in \mathbb{R}^{n'}$ for any $n' \geq n$

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$A \cdot X \geq b$$

$$X \succeq 0$$

Example

$$\min \quad 5y_1 + 6y_2 + 7y_3$$

$$y_1 + 3y_2 + 4y_3 \geq 5$$

$$2y_1 + 3y_2 + y_3 \geq 10$$

$$3y_1 + 2y_2 + 2y_3 \geq 7$$

$$\begin{pmatrix} y_1 & y_2 \\ y_2 & y_3 \end{pmatrix} \succeq 0$$

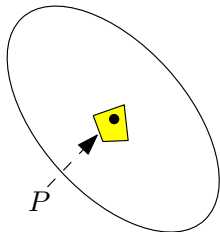
- $X \succeq 0 \iff X_{u,v} = X_{v,u}, \forall u, v \in [n]; (yy^T) \cdot X \geq 0, \forall y \in \mathbb{R}^n.$
- SDP \equiv LP with infinite number of linear constraints

Seperation Oracle \mathcal{O}

- Given a symmetric $X \in \mathbb{R}^{n \times n}$, we need to either claim $X \succeq 0$, or return a $y \in \mathbb{R}^n$ such that $y^T X y < 0$.
- QR decomposition finds eigenvalues and eigenvectors of X .

Recall: Ellipsoid Method

- maintain an ellipsoid that contains the feasible region
- query \mathcal{O} if the center of ellipsoid is in the feasible region:
 - yes: then the feasible region is not empty
 - no: cut the ellipsoid in half, find smaller ellipsoid to enclose the half-ellipsoid, and repeat

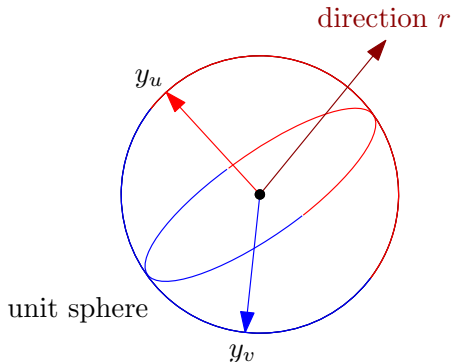


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SDP for Max-Cut

$$\begin{aligned} \max \quad & \frac{1}{2} \sum_{uv \in E} (1 - \langle y_u, y_v \rangle) \\ & |y_v| = 1 \quad \forall v \in V \end{aligned}$$



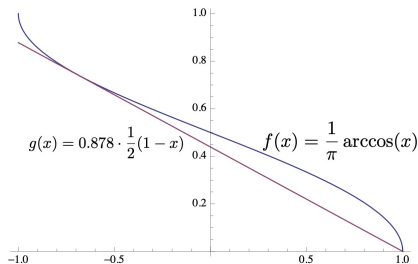
- let $(y_v)_{v \in V}$ be the vectors obtained from solving SDP
- $\text{sdp} = \frac{1}{2} \sum_{uv \in E} (1 - y_u^T y_v) \geq \text{opt}$

[Goemans-Williamson'95] Rounding Algorithm

- 1: randomly choose a **direction** $r \in \mathbb{R}^n$:
 - choose each $r_u \sim N(0, 1)$ i.i.d
 $N(0, 1)$: standard normal distribution
- 2: $\bar{y}_v = \text{sgn}(\langle y_v, r \rangle)$, $S = \{v \in V : \bar{y}_v > 0\}$, **return** $(S, V \setminus S)$

$$\Pr[uv \text{ is cut}] = \frac{\text{radian angle between } y_u \text{ and } y_v}{\pi} = \frac{\arccos\langle y_u, y_v \rangle}{\pi}$$

$$\begin{aligned} \frac{\Pr[uv \text{ is cut}]}{\frac{1}{2}(1 - \langle y_u, y_v \rangle)} &= \frac{\frac{1}{\pi} \arccos\langle y_u, y_v \rangle}{\frac{1}{2}(1 - \langle y_u, y_v \rangle)} \\ &= \frac{\frac{1}{\pi} \arccos(x)}{\frac{1}{2}(1 - x)} \\ x &:= \langle y_u, y_v \rangle \in [-1, 1] \end{aligned}$$



- $\alpha_{\text{GW}} := \inf_{x \in [-1, 1]} \frac{2}{\pi} \cdot \frac{\arccos(x)}{(1-x)} \geq 0.878$

$$\begin{aligned}\mathbb{E}[|E(S, T)|] &= \sum_{uv \in E} \Pr[uv \text{ is cut}] \geq \alpha_{\text{GW}} \sum_{uv \in E} \frac{1}{2}(1 - \langle y_u, y_v \rangle) \\ &= \alpha_{\text{GW}} \cdot \text{sdp} \geq \alpha_{\text{GW}} \cdot \text{opt} \geq 0.878 \cdot \text{opt}.\end{aligned}$$

- Assuming Unique Game Conjecture (UGC), no polynomial-time algorithm can give an approximation ratio of $\alpha_{\text{GW}} + \epsilon$ for any constant $\epsilon > 0$.

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Duality for Semi-Definite Programming

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$A \cdot X \geq b$$

$$X \succeq 0$$

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$\sum_{u,v \in [n]} a_{k,u,v} X_{u,v} \geq b \quad \forall k \in [m]$$

$$\sum_{u,v \in [n]} r_u r_v X_{u,v} \geq 0 \quad \forall r \in \mathbb{R}^n$$

- replace $X \succeq 0$ with infinite number of linear constraints:
 $(r^T r) \cdot X \geq 0, \forall r \in \mathbb{R}^n$.
- no symmetry constraint as A_k 's and c are symmetric

Duality for Semi-Definite Programming

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$A \cdot X \geq b$$

$$X \succeq 0$$

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$\sum_{u,v \in [n]} a_{k,u,v} X_{u,v} \geq b \quad \forall k \in [m]$$

$$\sum_{u,v \in [n]} r_u r_v X_{u,v} \geq 0 \quad \forall r \in \mathbb{R}^n$$

Dual :

$$\max \quad \sum_{k=1}^m b_k \cdot y_k$$

$$\sum_{k=1}^m a_{k,u,v} \cdot y_k + \sum_{r \in \mathbb{R}^n} r_u r_v \cdot z_r = c_{u,v} \quad \forall u, v \in [n]$$

$$y_k \geq 0 \quad \forall k \in [m]$$

$$z_r \geq 0 \quad \forall r \in \mathbb{R}^n$$

Duality for Semi-Definite Programming

Dual : $\max \quad \sum_{k=1}^m b_k \cdot y_k$

$$\sum_{k=1}^m a_{k,u,v} \cdot y_k + \sum_{r \in \mathbb{R}^n} r_u r_v \cdot z_r = c_{u,v} \quad \forall u, v \in [n]$$

$$y_k \geq 0 \quad \forall k \in [m]$$

$$z_r \geq 0 \quad \forall r \in \mathbb{R}^n$$

- \mathbb{R}^n is infinite. So the notion $\sum_{r \in \mathbb{R}^n}$ is bad. Informal.
- first red constraint $\Leftrightarrow A^T y + \sum_{r \in \mathbb{R}^n} z_r \cdot r r^T = c$
- $\sum_{r \in \mathbb{R}^n} z_r \cdot r r^T$ is PSD
- moreover, any PSD matrix can be written in this form
- \Rightarrow red constraints can be replaced by $A^T y \preceq c$

Duality for Semi-Definite Programming

Semi-Definite Program

$$\min \quad c^T \cdot X$$

$$A \cdot X \succeq b$$

$$X \succeq 0$$

Dual for SDP

$$\max \quad b^T y$$

$$A^T y \preceq c$$

$$y \geq 0$$

- Linear Program: $X \succeq 0$
- In Dual of LP: $A^T y \leq c$

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Focus on \mathbb{R}^n :

- axis-aligned ellipsoid centered at c with axis lengths

$$\mathcal{Q}_{c,a} := a \in \mathbb{R}_{>0}^n: \left\{ x \in \mathbb{R}^n : \sum_{i \in [n]} \frac{(x_i - c_i)^2}{a_i^2} \leq 1 \right\}$$

- axis-aligned half-ellipsoid:

$$\mathcal{R}_{c,a,w} := \{ x \in \mathcal{Q}_{c,a} : w^T(x - c) \geq 0 \}, w \in \mathbb{R}^n$$

Lemma For any axis-aligned half-ellipsoid $\mathcal{R}_{c,a,w}$, we can efficiently find an axis-aligned ellipsoid $\mathcal{Q}_{c',a'}$ such that

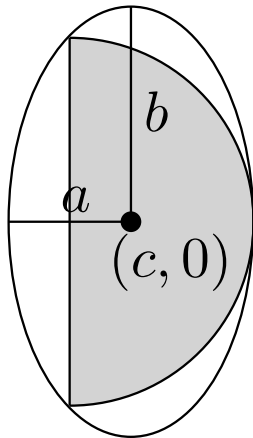
- $\mathcal{R}_{c,a,w} \subseteq \mathcal{Q}_{c',a'}$
- $\frac{\text{vol}(\mathcal{Q}_{c',a'})}{\text{vol}(\mathcal{Q}_{c,a})} \leq e^{-\frac{1}{2(n+1)}} = 1 - \Omega\left(\frac{1}{n}\right)$

Proof.

- we can assume $c = 0, a = 1$ and $w = (1, 0, 0, 0, \dots, 0)^T$.
- half-ellipsoid becomes half ball: $\{x \in \mathbb{R}^n : |x|_2 \leq 1, x_1 \geq 0\}$

Proof.

- center of new ellipsoid : $(c, 0, \dots, 0)$, $c \in [0, 1]$
- axis lengths: (a, b, b, \dots, b) , $a < b$
- the ellipsoid: $\frac{(x_1 - c)^2}{a^2} + \sum_{i=2}^n \frac{x_i^2}{b^2} \leq 1$
- $(1, 0, 0, \dots, 0)$ in ellipsoid: $\frac{(1-c)^2}{a^2} \leq 1$
- $(0, 1, 0, \dots, 0)$ in ellipsoid: $\frac{c^2}{a^2} + \frac{1}{b^2} \leq 1$
- set a, b and c so that both constraints are tight: $a = 1 - c, b = \sqrt{\frac{(1-c)^2}{(1-c)^2 - c^2}} = \frac{1-c}{\sqrt{1-2c}}$



Proof.

- we won't prove that the ellipsoid contains all points in half ball.
- volume of ellipsoid is minimized when $c = \frac{1}{n+1}$
- $a = \frac{n}{n+1}, b = \frac{n/(n+1)}{\sqrt{(n-1)/(n+1)}}$

Proof.

- $a = \frac{n}{n+1}, b = \frac{n/(n+1)}{\sqrt{(n-1)/(n+1)}}$

$$\begin{aligned}\frac{\text{vol}(\text{ellipsoid})}{\text{vol}(\text{unit ball})} &= ab^{n-1} = \left(\frac{n}{n+1}\right)^n \cdot \left(\frac{n+1}{n-1}\right)^{\frac{n-1}{2}} \\ &= \left(\frac{n^2}{n^2-1}\right)^{\frac{n-1}{2}} \cdot \frac{n}{n+1}\end{aligned}$$

$$\begin{aligned}\ln \frac{\text{vol}(\text{ellipsoid})}{\text{vol}(\text{unit ball})} &= \frac{n-1}{2} \ln \frac{n^2}{n^2-1} + \ln \frac{n}{n+1} \\ &\leq \frac{n-1}{2} \cdot \frac{1}{n^2-1} - \frac{1}{n+1} = -\frac{1}{2(n+1)}\end{aligned}$$

- we used $\ln(1+x) \leq x, \forall x > -1$

- $\frac{\text{vol}(\text{ellipsoid})}{\text{vol}(\text{unit ball})} \leq e^{-\frac{1}{2(n+1)}}$



Lemma For any axis-aligned half-ellipsoid $\mathcal{R}_{c,a,w}$, we can efficiently find an axis-aligned ellipsoid $\mathcal{Q}_{c',a'}$ such that

- $\mathcal{R}_{c,a,w} \subseteq \mathcal{Q}_{c',a'}$
- $\frac{\text{vol}(\mathcal{Q}_{c',a'})}{\text{vol}(\mathcal{Q}_{c,a})} \leq e^{-\frac{1}{2(n+1)}} = 1 - \Omega\left(\frac{1}{n}\right)$

Assumption

- The initial polytope is contained in a ball of radius R , where $R \leq 2^{\text{poly}(\text{input size})}$.
- When the polytope is not empty, it contains a ball of radius at least r , where $r \geq 1/2^{\text{poly}(\text{input size})}$.
- The first assumption is easy to guarantee; the second assumption needs some twisting.
- we can stop the ellipsoid algorithm when volume is less than the volume of a ball of radius r

- $R \leq 2^{\text{poly}(\text{input size})}$, $r \geq 1/2^{\text{poly}(\text{input size})}$
- number of iterations for ellipsoid method is at most

$$\ln_{e^{\frac{1}{2(n+1)}}} \left(\frac{R}{r} \right)^n = n \cdot \frac{\ln(R/r)}{1/(2(n+1))} = O(n^2) \cdot \ln \frac{R}{r} \\ \leq O(n^2) \cdot \text{poly}(\text{input size})$$